



کالا صنعتی



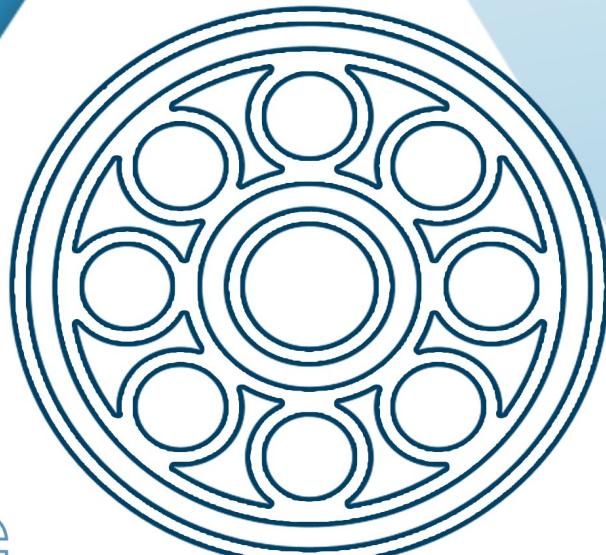
# SCHAEFFLER

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Catalog 2021



## BULL BEARING

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# SCHAEFFLER



Ball bearing

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# 1 Self-aligning ball bearings



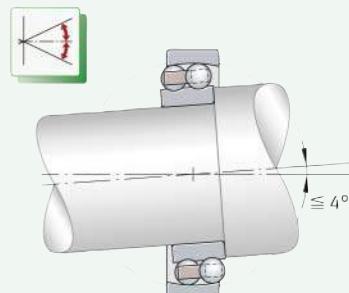
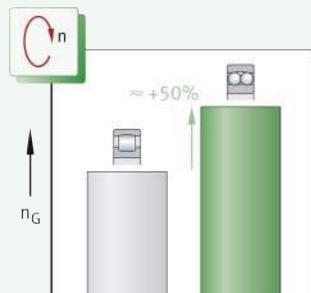
Self-aligning ball bearings are particularly suitable:

- if there is skewing between the outer and inner ring (for the compensation of angular misalignments) ► 372 | 1.3
- for bearing arrangements with high radial loads ► 372 | 1.2
- for higher speeds on account of their point contact, than barrel roller bearings with line contact
- where bearings with the above-mentioned characteristics are expected to run more quietly and at lower temperatures, even at high speeds.

For an overview of other product-specific features, see the Matrix for bearing preselection ► 369.

 1  
*Self-aligning ball bearing:  
speed comparison with barrel  
roller bearing, compensation  
of misalignments*

$n_G$  = limiting speed



## 1.1 Bearing design

### Design variants

Self-aligning ball bearings are available as:

- bearings of basic design ► 371 | □ 2
- bearings with extended inner ring and locating slot ► 371 | □ 3
- bearings with adapter sleeve ► 371 | □ 4
- bearings with ball projection ► 372 | □ 5.

### Bearings of basic design

#### The outer ring has a curved raceway

Self-aligning ball bearings are double row, self-retaining radial ball bearings, which are part of the group of self-aligning bearings. The outer ring has a single concave raceway for the two rows of balls. As a result, the bearings permit the compensation of static and dynamic angular misalignments (skewing between the inner and outer ring) within certain limits ► 372 | 1.3. The inner ring has two formed raceway grooves in which the rolling elements run. Solid cages made from polyamide PA66 or brass are used ► 375 | □ 2.

#### The bore is cylindrical or tapered

Bearings of basic design are supplied with a cylindrical bore; self-aligning ball bearings of series 12, 13, 22 and 23 are also available with a tapered bore ► 371 | □ 2.

Bearings with a tapered bore have a bore taper of 1:12 and the suffix K ► 377 | □ 5.





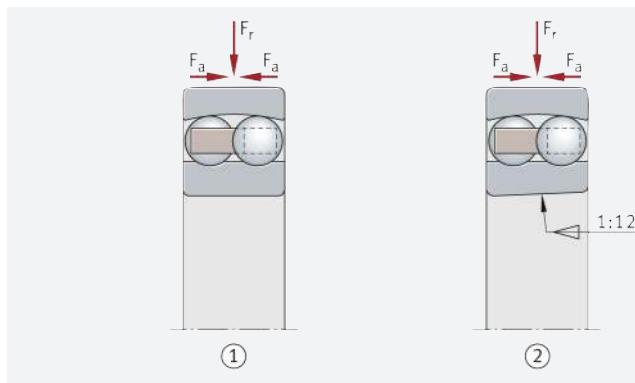
## Self-aligning ball bearings of basic design

$F_r$  = radial load

$F_a$  = axial load

① Self-aligning ball bearing with cylindrical bore, open

② Self-aligning ball bearing with tapered bore, open, bore taper 1:12



## Suitable for simple bearing arrangements

### Bearings with extended inner ring and locating slot

Self-aligning ball bearings of series 112 have an extended inner ring with cylindrical bore on both sides and a slot on one side of the inner ring ► 371 |  3. These bearings are particularly suitable for simple bearing arrangements with conventional shafts. Due to the bearing bore tolerance J7, mounting and dismantling of this type is very simple. The slot is used to locate the bearings in an axial direction by means of a grub screw; ► 380 |  8.

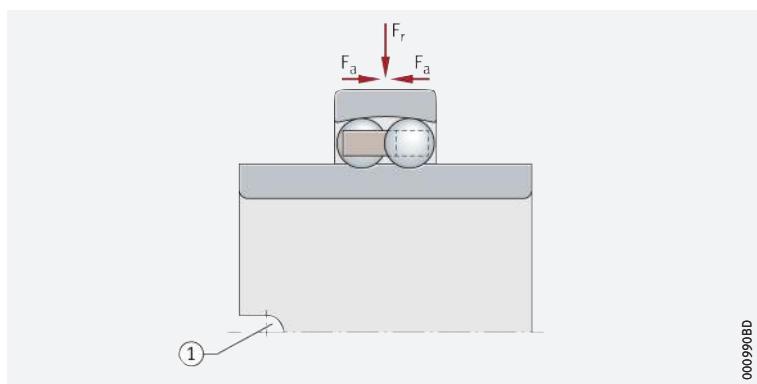


## Self-aligning ball bearing with extended inner ring and locating slot

$F_r$  = radial load

$F_a$  = axial load

① Locating slot



## Ready-to-fit bearing mounting kits facilitate the ordering and mounting of self-aligning ball bearings

### Bearings with adapter sleeve

Complete bearing mounting kits are also available for use in locating self-aligning ball bearings with a tapered bore on a cylindrical shaft journal. These units comprise the bearing, slotted adapter sleeve, tab washer and locknut (series 12..-K + H, 13..-K + H, 22..-K + H, 23..-K + H, 22..-K-2RS + H) ► 371 |  4. Adapter sleeves allow bearings to be located on smooth and stepped shafts. The adapter sleeves must also be stated when placing the order. Ordering example ► 377 |  7.

## Self-aligning ball bearings with adapter sleeve

$F_r$  = radial load

$F_a$  = axial load

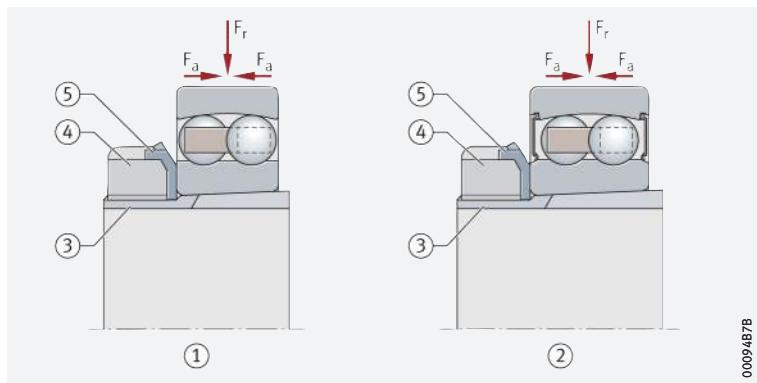
① Self-aligning ball bearing, open

② Self-aligning ball bearing, lip seal on both sides

③ Adapter sleeve

④ Locknut

⑤ Tab washer



### Bearings with ball projection

- ☞ *The dimension  $C_1$  must be observed*

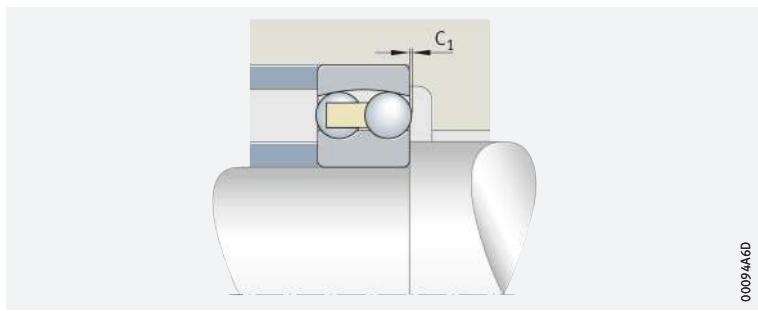


5  
*Self-aligning ball bearing with ball projection*

$C_1$  = ball projection



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## 1.2 Load carrying capacity

- ☞ *Suitable for high radial and low axial loads*

In addition to high radial forces, self-aligning ball bearings also support low axial forces from both directions ►371|② to ►371|④. Due to the point contact with which the rolling elements are in contact with the raceways, the radial load carrying capacity of the bearings is lower than for barrel roller bearings with line contact.

### Axial load carrying capacity of bearings with adapter sleeve

Where bearings with adapter sleeves are located on a smooth shaft without a fixed stop (e.g. rigid shoulder), their axial load carrying capacity is dependent on the friction between the shaft and the sleeve.



If there is any doubt about the axial load carrying capacity of the location method, please consult Schaeffler.

## 1.3 Compensation of angular misalignments

- ☞ *Self-aligning ball bearings compensate dynamic and static angular misalignments*

Due to the concave rolling element raceway in the outer ring, self-aligning ball bearings are capable of angular adjustment. As a result, they permit skewing between the outer and inner ring within certain limits, without causing damage to the bearings, and can thus compensate misalignments, shaft deflections and housing deformations.

### Permissible adjustment angle

Under normal operating conditions and with a rotating inner ring, self-aligning ball bearings can swivel up to 4° from their central position, whereas sealed bearings can swivel up to 1,5°. The extent to which these values can be used in practice is, however, essentially dependent on the design of the bearing arrangement.



If the outer ring rotates or the inner ring undergoes tumbling motion, the angular adjustment facility is considerably smaller. In such cases, please consult Schaeffler.

## 1.4 Lubrication

### ⦿ Greased bearings are maintenance-free

Sealed self-aligning ball bearings are lubricated with a high quality lithium soap grease with a mineral oil base, which has good anti-corrosion characteristics. The grease filling is measured so that it is sufficient for the entire life of the bearing. As a result, these bearings are maintenance-free.



Do not wash greased bearings out prior to mounting. If mounting is carried out using thermal tools, the bearings should not be heated to a temperature in excess of +80 °C, taking account of the grease filling and seal material. If higher heating temperatures are required, it must be ensured that the permissible upper temperature limits for grease and seals are not exceeded. Schaeffler recommends the use of induction heating devices for heating purposes ➤ 231.

### ⦿ Lubrication for ungreased bearings

#### ⦿ Compatibility with plastic cages



Open bearings are not greased. They can be lubricated from the end faces using oil or grease.

When using bearings with plastic cages, compatibility between the lubricant and the cage material must be ensured if synthetic oils, lubricating greases with a synthetic oil base or lubricants containing a high proportion of EP additives are used.

### ⦿ Observe oil change intervals

Aged oil and additives in the oil can impair the operating life of plastics at high temperatures. As a result, stipulated oil change intervals must be strictly observed.

## 1.5 Sealing

### ⦿ Also available with lip seals

Self-aligning ball bearings of series 22 and 23 are also available with contact seals on both sides of the bearing ➤ 371 | □ 4. The integration of such seals into the bearing provides a compact, economical and reliable solution for the sealing of bearing arrangements. In order that the highest possible sealing effect can still be achieved with minimum friction, the seal lips are in contact with the ground opposing running surface of the inner ring under light pressure. The sealing material used is the proven, oil-resistant and wear-resistant elastomer material NBR. Sealed self-aligning ball bearings have the suffix 2RS ➤ 377 | ■ 5.

### ⦿ Sealing can be achieved in the adjacent construction, if the bearings are open

In the case of unsealed bearings, sealing of the bearing position must be carried out in the adjacent construction. The sealing system should reliably prevent:

- moisture and contaminants from entering the bearing
- the egress of lubricant from the bearing.



## 1.6 Speeds

 **Speeds  
in the product tables**



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The product tables give two speeds for most bearings ► 386 | 

- the kinematic limiting speed  $n_G$
- the thermal speed rating  $n_{\vartheta r}$

### Limiting speeds

The limiting speed  $n_G$  is the kinematically permissible speed of the bearing. Even under favourable mounting and operating conditions, this value should not be exceeded without prior consultation with Schaeffler ► 64.

The values given in the product tables are valid for oil lubrication in the case of bearings without seals and for grease lubrication where bearings are supplied greased and with seals.

 **Values for grease  
lubrication**

  **$n_{\vartheta r}$  is used to calculate  $n_G$**

 **Bearings with contact seals**

For grease lubrication, 85% of the value stated in the product tables is permissible in each case.

### Reference speeds

The thermal speed rating  $n_{\vartheta r}$  is not an application-oriented speed limit, but is a calculated ancillary value for determining the thermally safe operating speed  $n_{\vartheta}$  ► 64.

For bearings with contact seals, no reference speeds are defined in accordance with DIN ISO 15312:2004. As a result, only the limiting speed  $n_G$  is given in the product tables for these bearings.

## 1.7 Noise

### Schaeffler Noise Index

The Schaeffler Noise Index (SGI) is not yet available for this bearing type ► 69. The data for these bearing series will be introduced and updated in stages.

Further information:

- **medias** ► <https://medias.schaeffler.com>.

## 1.8 Temperature range

 **Limiting values**

The operating temperature of the bearings is limited by:

- the dimensional stability of the bearing rings and rolling elements
- the cage
- the lubricant
- the seals.

Possible operating temperatures of self-aligning ball bearings ► 675 |  5.

 **1**  
*Permissible temperature ranges*

Operating temperature	Open self-aligning ball bearings		Sealed self-aligning ball bearings
	with brass cage	with polyamide cage PA66	
	-30 °C to +150 °C	-30 °C to +120 °C	-30 °C to +100 °C, limited by the lubricant and seal material



In the event of anticipated temperatures which lie outside the stated values, please contact Schaeffler.

## 1.9 Cages

 Solid cages made from brass and polyamide PA66 are used as standard

 2 Cage, cage suffix, bore code



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Standard cages and additional cage designs for self-aligning ball bearings ►375| 2. Other cage designs are available by agreement. With such cages, however, suitability for high speeds and temperatures as well as the basic load ratings may differ from the values for the bearings with standard cages.

For high continuous temperatures and applications with difficult operating conditions, bearings with brass or sheet steel cages should be used. If there is any uncertainty regarding cage suitability, please consult Schaeffler.

Bearing series	Solid cage made from polyamide PA66	Solid brass cage	
	TVH standard	M	also available for
		standard	
Bore code			
10	8	–	–
12	up to 18	from 19	–
13	up to 13	from 14	03
22	up to 16, 18	17, from 19	12, 14
23	up to 13	from 14	05 to 10, 12, 13
112	04 to 12	–	–

## 1.10 Internal clearance

 The standard is CN



 3 Radial internal clearance of self-aligning ball bearings with cylindrical bore

### Radial internal clearance – bearings with cylindrical bore

Self-aligning ball bearings with cylindrical bore are manufactured as standard with radial internal clearance CN (normal) ►375| 3. CN is not stated in the designation.

Certain sizes are also available by agreement with the larger internal clearance C3.

The values for radial internal clearance correspond to DIN 620-4:2004 (ISO 5753-1:2009) ►375| 3. They are valid for bearings which are free from load and measurement forces (without elastic deformation).

Nominal bore diameter d mm		Radial internal clearance			
		CN (Group N) μm		C3 (Group 3) μm	
over	incl.	min.	max.	min.	max.
–	6	5	15	10	20
6	10	6	17	12	25
10	14	6	19	13	26
14	18	8	21	15	28
18	24	10	23	17	30
24	30	11	24	19	35
30	40	13	29	23	40
40	50	14	31	25	44
50	65	16	36	30	50
65	80	18	40	35	60
80	100	22	48	42	70
100	120	25	56	50	83
120	140	30	68	60	100
140	160	35	80	70	120

✉ **The standard is C3**

**Radial internal clearance – bearings with tapered bore**

Self-aligning ball bearings with tapered bore are manufactured as standard with the larger radial internal clearance C3 ► 376 | 4.



Certain sizes are also available by agreement with internal clearance CN (normal).



The values for radial internal clearance correspond to DIN 620-4:2004 (ISO 5753-1:2009) ► 376 | 4. They are valid for bearings which are free from load and measurement forces (without elastic deformation).



*Radial internal clearance  
of self-aligning ball bearings  
with tapered bore*



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Nominal bore diameter		Radial internal clearance			
d mm		CN (Group N) μm		C3 (Group 3) μm	
over	incl.	min.	max.	min.	max.
18	24	13	26	20	33
24	30	15	28	23	39
30	40	19	35	29	46
40	50	22	39	33	52
50	65	27	47	41	61
65	80	35	57	50	75
80	100	42	68	62	90
100	120	50	81	75	108
120	140	60	98	90	130
140	160	65	110	100	150

## 1.11 Dimensions, tolerances

**Dimension standards**



The main dimensions of self-aligning ball bearings correspond to DIN 630:2011, with the exception of bearing series 112.

Nominal dimensions of self-aligning ball bearings ► 386 | 4.

✉ **Series 112**

The dimensions of self-aligning ball bearings with extended inner ring (bearing series 112) correspond to DIN 630-2, which was withdrawn in 1993. Nominal dimensions of bearings ► 400 | 4.

**Chamfer dimensions**



The limiting dimensions for chamfer dimensions correspond to DIN 620-6:2004. Overview and limiting values ► 135 | 7.11.

Nominal value of chamfer dimension ► 386 | 4.

**Tolerances**



The tolerances for the dimensional and running accuracy of self-aligning ball bearings correspond to tolerance class Normal in accordance with ISO 492:2014, except for the bearing bore of bearing series 112, which is manufactured to tolerance class J7. Tolerance values in accordance with ISO 492 ► 122 | 8.

## 1.12 Suffixes

For a description of the suffixes used in this chapter ► 377 | 5 and **medias** interchange ► <https://www.schaeffler.de/std/1D52>.

 5  
Suffixes and corresponding descriptions

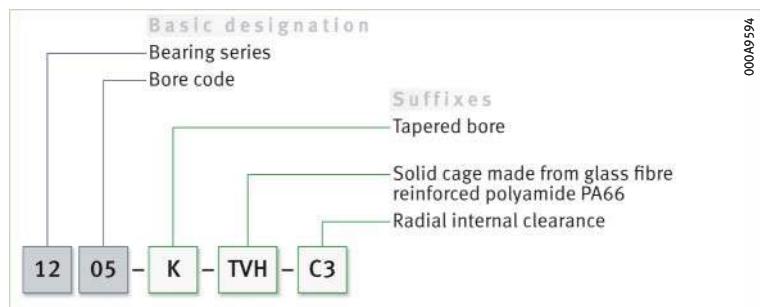
Suffix	Description of suffix	
C3	Radial internal clearance C3 (larger than normal)	Standard for bearings with tapered bore
CN	Radial internal clearance CN (normal)	Special design for bearings with tapered bore, available by agreement
K	Tapered bore	Standard
M	Solid brass cage	Standard,
TVH	Solid cage made from glass fibre reinforced polyamide PA66	cage material dependent on bearing series and bore code
2RS	Contact seal on both sides	Dependent on bearing series

## 1.13 Structure of bearing designation

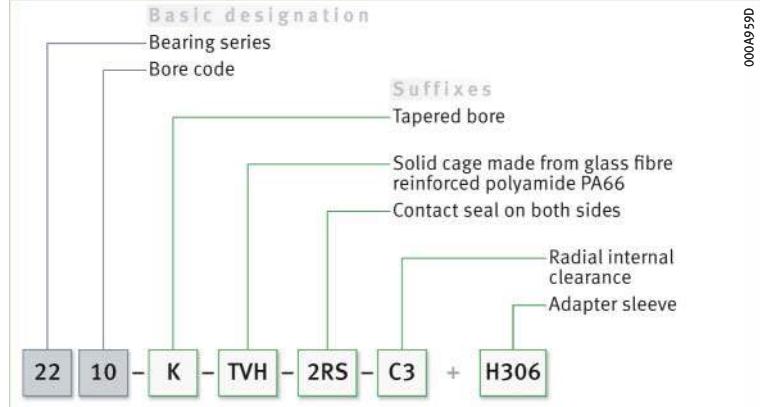
 Examples of composition of bearing designation

The designation of bearings follows a set model. Examples ► 377 | 6 and ► 377 | 7. The composition of designations is subject to DIN 623-1 ► 102 | 10.

 6  
Self-aligning ball bearing with tapered bore: designation structure



 7  
Self-aligning ball bearing with tapered bore and adapter sleeve: designation structure



## 1.14 Dimensioning

### Equivalent dynamic bearing load

☞ *P = F<sub>r</sub> under purely radial load of constant magnitude and direction*

☞ *P is a substitute force for combined load and various load cases*

☞ *F<sub>a</sub>/F<sub>r</sub> ≤ e or F<sub>a</sub>/F<sub>r</sub> > e*

**f1 1**  
Equivalent dynamic load

$$\frac{F_a}{F_r} \leq e \Rightarrow P = F_r + Y_1 \cdot F_a$$

**f1 2**  
Equivalent dynamic load

$$\frac{F_a}{F_r} > e \Rightarrow P = 0,65 \cdot F_r + Y_2 \cdot F_a$$

#### Legend

P	N	Equivalent dynamic bearing load
F <sub>r</sub>	N	Radial load
F <sub>a</sub>	N	Axial load
e, Y <sub>1</sub> , Y <sub>2</sub>	-	Factors ► 386   ■■■



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**f1 3**  
Equivalent static load

$$P_0 = F_{0r} + Y_0 \cdot F_{0a}$$

#### Legend

P <sub>0</sub>	N	Equivalent static bearing load
F <sub>0r</sub> , F <sub>0a</sub>	N	Largest radial or axial load present (maximum load)
Y <sub>0</sub>	-	Axial load factor ► 386   ■■■

### Static load safety factor

☞ *S<sub>0</sub> = C<sub>0</sub>/P<sub>0</sub>*

**f1 4**  
Static load safety factor

$$S_0 = \frac{C_0}{P_0}$$

#### Legend

S <sub>0</sub>	-	Static load safety factor
C <sub>0</sub>	N	Basic static load rating
P <sub>0</sub>	N	Equivalent static bearing load.

## 1.15 Minimum load

In order that no slippage occurs between the contact partners, the self-aligning ball bearings must be constantly subjected to a sufficiently high load. Based on experience, a minimum radial load of the order of  $P > C_{0r}/100$  is thus necessary. In most cases, however, the radial load is already higher than the requisite minimum load due to the weight of the supported parts and the external forces.



If the minimum radial load is lower than indicated above, please consult Schaeffler.

## 1.16

# Design of bearing arrangements

☞ *Support bearing rings over their entire circumference and width*

In order to allow full utilisation of the load carrying capacity of the bearings and achieve the requisite rating life, the bearing rings must be rigidly and uniformly supported by means of contact surfaces over their entire circumference and over the entire width of the raceway. Support can be provided by means of a cylindrical or tapered seating surface ▶ 380 | □ 8 to ▶ 381 | □ 11. The seating and contact surfaces should not be interrupted by grooves, holes or other recesses. The accuracy of mating parts must meet specific requirements ▶ 381 | □ 6 to ▶ 382 | □ 8.

## Radial location – fit recommendations for bearings with cylindrical bore

☞ *For secure radial location, tight fits are necessary*

In addition to supporting the rings adequately, the bearings must also be securely located in a radial direction, to prevent creep of the bearing rings on the mating parts under load. This is generally achieved by means of tight fits between the bearing rings and the mating parts. If the rings are not secured adequately or correctly, this can cause severe damage to the bearings and adjacent machine parts. Influencing factors, such as the conditions of rotation, magnitude of the load, internal clearance, temperature conditions, design of the mating parts and the mounting and dismounting options must be taken into consideration in the selection of fits.



If shock type loads occur, tight fits (transition fit or interference fit) are required to prevent the rings from coming loose at any point. Clearance, transition or interference fits ▶ 150 | □ 6 and ▶ 158 | □ 7.



The following information provided in Technical principles must be taken into consideration in the design of bearing arrangements:

- conditions of rotation ▶ 145
- tolerance classes for cylindrical shaft seats (radial bearings) ▶ 147 | □ 2
- shaft fits ▶ 150 | □ 6
- tolerance classes for bearing seats in housings (radial bearings) ▶ 148 | □ 4
- housing fits ▶ 158 | □ 7
- shaft tolerances for adapter sleeves and withdrawal sleeves ▶ 166 | □ 8.

## Axial location – location methods for bearings with cylindrical bore

☞ *The bearings must also be securely located in an axial direction*

As a tight fit alone is not normally sufficient to also locate the bearing rings securely on the shaft and in the housing bore in an axial direction, this must usually be achieved by means of an additional axial location or retention method. The axial location of the bearing rings must be matched to the type of bearing arrangement. Shaft and housing shoulders, housing covers, nuts, spacer rings, retaining rings, adapter and withdrawal sleeves etc., are fundamentally suitable.



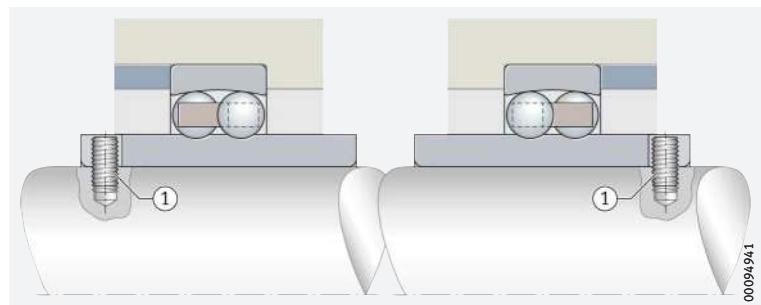
### Axial location – bearing series 112

☞ Simple location by means of a grub screw



**8**  
*Axial location of bearing series 112 using grub screw and arrangement of self-aligning ball bearings, where a shaft is supported by two bearings*

① Grub screw



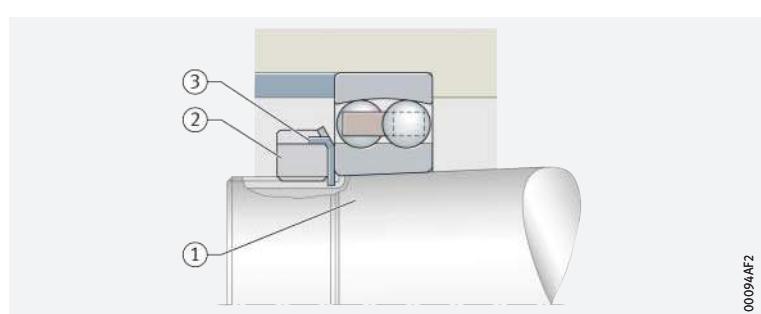
### Axial location – bearings with tapered bore

☞ Location by means of locknut and tab washer



**9**  
*Self-aligning ball bearing with tapered bore, mounted directly on the tapered shaft journal*

① Tapered journal with fixing thread  
② Locknut  
③ Tab washer



### Location of bearings by means of adapter sleeve

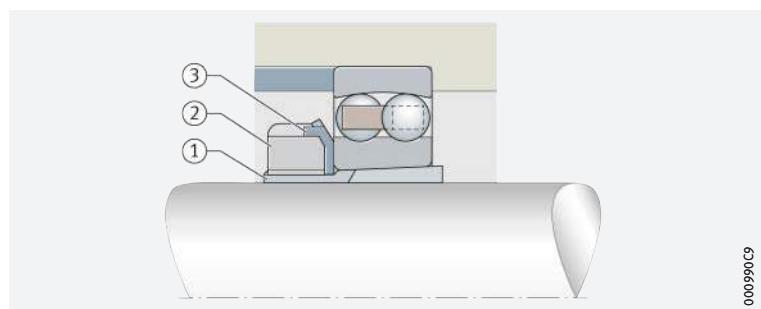
☞ Mounting can be carried out quickly and reliably by means of wrench sets from Schaeffler

Self-aligning ball bearings with a tapered bore can be located easily and with operational liability on smooth or stepped cylindrical shafts by means of an adapter sleeve ► 380 | 10. The adapter sleeve does not need to be secured on the shaft by any additional means. The bearings can be positioned at any point on smooth shafts. Axial load carrying capacity of bearing arrangements by means of adapter sleeve connection ► 372 | 1.2.



**10**  
*Self-aligning ball bearing with adapter sleeve located on smooth shaft*

① Adapter sleeve  
② Locknut  
③ Tab washer





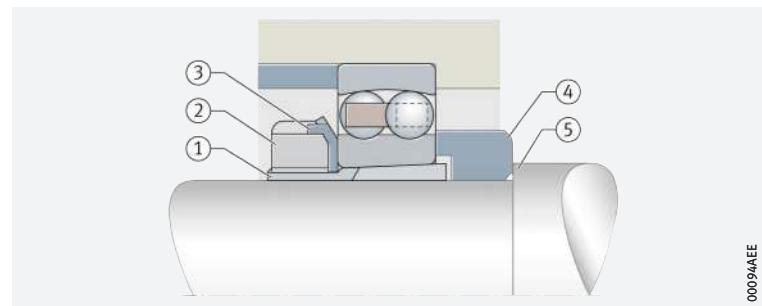
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### 11 Stepped shaft, axial abutment by means of a support ring

- ① Adapter sleeve
- ② Locknut
- ③ Tab washer
- ④ Support ring
- ⑤ Shaft shoulder

#### Location by means of adapter sleeve, axial abutment by means of a support ring

If very high axial forces are present, a support ring can also be used to provide axial abutment ►381|□ 11. In this instance, the mounting dimensions of the support ring  $B_a$  and  $d_b$  in the product tables must be observed ►386|■.



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#### Dimensional, geometrical and running accuracy of cylindrical bearing seats

⌚ A minimum of IT6 should be provided for the shaft seat and a minimum of IT7 for the housing seat

The accuracy of the cylindrical bearing seat on the shaft and in the housing should correspond to the accuracy of the bearing used. For self-aligning ball bearings with the tolerance class Normal, the shaft seat should correspond to a minimum of standard tolerance grade IT6 and the housing seat to a minimum of IT7. Guide values for the geometrical and positional tolerances of bearing seating surfaces ►381|■ 6, tolerances  $t_1$  to  $t_3$  in accordance with ►168|□ 11. Numerical values for IT grades ►381|■ 7.

### 6 Guide values for the geometrical and positional tolerances of bearing seating surfaces

Bearing tolerance class		Bearing seating surface	Standard tolerance grades to ISO 286-1 (IT grades)			
to ISO 492	to DIN 620		Diameter tolerance	Roundness tolerance	Parallelism tolerance	Total axial runout tolerance of abutment shoulder
Normal	PN (P0)	Shaft	IT6 (IT5)	Circumferential load IT4/2	Circumferential load IT4/2	IT4
				Point load IT5/2	Point load IT5/2	
		Housing	IT7 (IT6)	Circumferential load IT5/2	Circumferential load IT5/2	IT5
				Point load IT6/2	Point load IT6/2	

### 7 Numerical values for ISO standard tolerances (IT grades) to ISO 286-1:2010

IT grade	Nominal dimension in mm						
	over 18 incl. 30	30	50	80	120	180	250
Values in $\mu\text{m}$							
IT4	6	7	8	10	12	14	16
IT5	9	11	13	15	18	20	23
IT6	13	16	19	22	25	29	32
IT7	21	25	30	35	40	46	52

## Roughness of cylindrical bearing seating surfaces

### Ra must not be too high

 8  
*Roughness values  
for cylindrical bearing seating  
surfaces – guide values*

Nominal diameter of the bearing seat d (D) mm		Recommended mean roughness value for ground bearing seats Ramax µm			
		Diameter tolerance (IT grade)			
over	incl.	IT7	IT6	IT5	IT4
–	80	1,6	0,8	0,4	0,2
80	500	1,6	1,6	0,8	0,4

## Tolerances for tapered bearing seats

### Specifications for tapered bearing seats

### The contact surfaces for the rings must be of sufficient height

For bearings located directly on a tapered shaft journal ► 380 | □ 9, the data are in accordance with ► 171 | □ 12.

## Mounting dimensions for the contact surfaces of bearing rings

The mounting dimensions of the shaft and housing shoulders, and spacer rings etc., must ensure that the contact surfaces for the bearing rings are of sufficient height. However, they must also reliably prevent rotating parts of the bearing from grazing stationary parts. Proven mounting dimensions for the radii and diameters of the abutment shoulders ► 386 | □ . These dimensions are limiting dimensions (maximum or minimum dimensions); the actual values should not be higher or lower than specified.

## Suitable bearing housings for self-aligning ball bearings

### A large range of housings is available



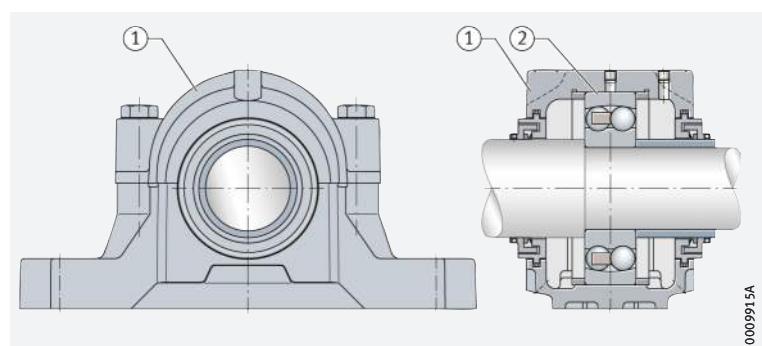
For economical, operationally reliable and easily interchangeable bearing arrangement units, the self-aligning ball bearings can also be combined with Schaeffler bearing housings ► 382 | □ 12. These easy-to-fit units fulfil all of the requirements for modern machine and plant designs with favourable maintenance-related characteristics.

Due to the large number of application areas, an extensive range of bearing housings is available for bearings with cylindrical and tapered bores. These include split and unsplit plummer block housings, take-up housings, flanged housings and housings for specific industrial and railway applications. Detailed information on bearing housings can be found in publication GK 1 ► <https://www.schaeffler.de/std/1D54>. This book can be ordered from Schaeffler.

### 12

### Split plummer block housing with a self-aligning ball bearing

- ① Split plummer block housing SNV
- ② Self-aligning ball bearing



## 1.17 Mounting and dismounting



The mounting and dismounting options for self-aligning ball bearings, by thermal, hydraulic or mechanical methods, must be taken into consideration in the design of the bearing position.

Ensure that the bearings are not damaged during mounting

Suitable methods

### Mounting of bearings with a tapered bore

Bearings with a tapered bore are mounted with a tight fit on the shaft or adapter and withdrawal sleeve. The measurement of the reduction in radial internal clearance or of the axial drive-up distance of the inner ring on the tapered bearing seat serves as an indication of the tight fit.

The measurement is usually carried out with a feeler gauge



### Measuring the reduction in radial internal clearance

The reduction in radial internal clearance is the difference between the radial internal clearance before mounting and the bearing clearance after mounting of the bearing ► 383 | 13. The radial internal clearance must be measured first. During pressing on, the radial clearance (bearing clearance) must be checked until the necessary reduction in the radial internal clearance and thus the required tight fit is achieved.

#### 13 Reduction in radial internal clearance

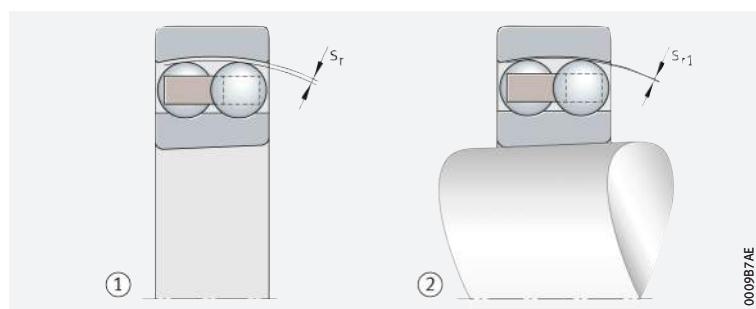
$s_r$  = radial internal clearance before mounting

$s_{r1}$  = radial internal clearance after mounting

$s_r - s_{r1}$  = reduction in radial internal clearance

① Before mounting

② After mounting



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### Measuring the axial drive-up distance

The axial drive-up distance can also be measured in place of the reduction in radial internal clearance ► 383 | 14.

#### 14 Axial drive-up distance

$s_a$  = axial press-on distance (axial drive-up distance of the bearing)

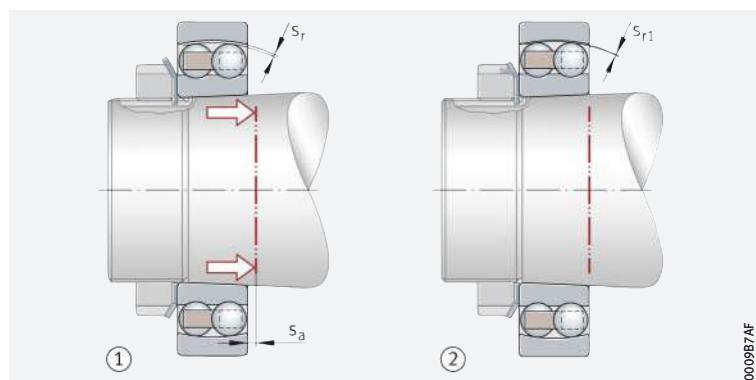
$s_r$  = radial internal clearance

$s_{r1}$  = radial internal clearance after pressing on

$s_r - s_{r1}$  = reduction in radial internal clearance

① Before pressing on

② After pressing on



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The malfunction-free operation of bearings presupposes that these have been mounted correctly. An insufficient operating clearance or inadequately tight fit on the shaft generally leads to bearing damage.



If there is any uncertainty regarding the practical application of both methods, Schaeffler must always be consulted.



The mounting of self-aligning ball bearings is also described in the Schaeffler publication BA 28. This BA publication can be requested from Schaeffler.



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### Schaeffler Mounting Handbook

Rolling bearings must be handled with great care



Rolling bearings are well-proven precision machine elements for the design of economical and reliable bearing arrangements, which offer high operational security. In order that these products can function correctly and achieve the envisaged operating life without detrimental effect, they must be handled with care.

The Schaeffler Mounting Handbook MH 1 gives comprehensive information about the correct storage, mounting, dismounting and maintenance of rotary rolling bearings ► <https://www.schaeffler.de/std/1D53>. It also provides information which should be observed by the designer, in relation to the mounting, dismounting and maintenance of bearings, in the original design of the bearing position. This book is available from Schaeffler on request.

## 1.18

### Legal notice regarding data freshness

The further development of products may also result in technical changes to catalogue products



Of central interest to Schaeffler is the further development and optimisation of its products and the satisfaction of its customers. In order that you, as the customer, can keep yourself optimally informed about the progress that is being made here and with regard to the current technical status of the products, we publish any product changes which differ from the printed version in our electronic product catalogue.

We therefore reserve the right to make changes to the data and illustrations in this catalogue. This catalogue reflects the status at the time of printing. More recent publications released by us (as printed or digital media) will automatically precede this catalogue if they involve the same subject. Therefore, please always use our electronic product catalogue to check whether more up-to-date information or modification notices exist for your desired product.

#### Link to electronic product catalogue



The following link will take you to the Schaeffler electronic product catalogue: ► <https://medias.schaeffler.com>.

## 1.19

### Further information



In addition to the data in this chapter, the following chapters in Technical principles must also be observed in the design of bearing arrangements:

- Determining the bearing size ► 34
- Rigidity ► 54
- Friction and increases in temperature ► 56
- Speeds ► 64
- Bearing data ► 97
- Lubrication ► 70
- Sealing ► 182
- Design of bearing arrangements ► 139
- Mounting and dismounting ► 191.



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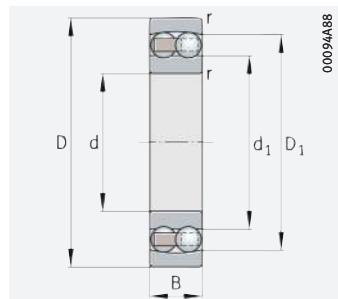


## Self-aligning ball bearings

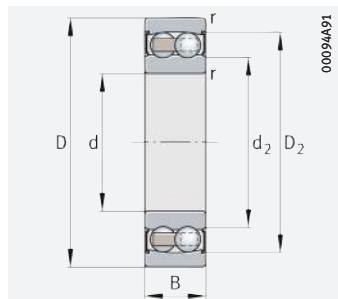
With cylindrical or tapered bore



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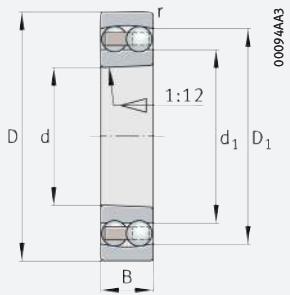
Cylindrical bore



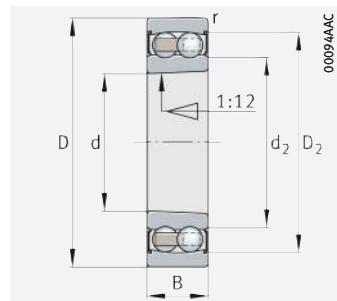
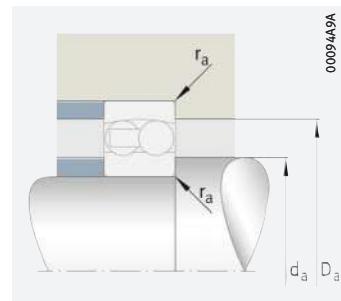
Cylindrical bore with seal 2RS

### d = 5 – 20 mm

Main dimensions			Basic load ratings		Fatigue limit load	Limiting speed	Speed rating	Mass	Designation
d	D	B	dyn. C <sub>r</sub> N	stat. C <sub>0r</sub> N	C <sub>ur</sub>	n <sub>G</sub> min <sup>-1</sup>	n <sub>θr</sub> min <sup>-1</sup>	m ≈ kg	
5	19	6	2 600	475	29,5	41 500	24 500	0,01	135-TVH
6	19	6	2 600	475	29,5	41 500	30 500	0,009	126-TVH
7	22	7	2 750	560	34,5	39 000	26 500	0,014	127-TVH
8	22	7	2 750	560	34,5	39 000	27 000	0,014	108-TVH
9	26	8	3 950	800	50	33 500	24 100	0,022	129-TVH
10	30	9	5 700	1 180	73	29 500	22 100	0,034	1200-TVH
	30	14	5 700	1 180	73	16 500	27 000	0,053	2200-2RS-TVH
	30	14	8 800	1 730	107	25 500	26 000	0,045	2200-TVH
12	32	10	5 700	1 250	78	28 000	21 300	0,041	1201-TVH
	32	14	5 700	1 250	78	14 700	27 000	0,058	2201-2RS-TVH
	32	14	9 400	1 920	120	24 200	23 300	0,05	2201-TVH
	37	12	9 800	2 140	133	22 300	16 200	0,067	1301-TVH
15	35	11	7 700	1 730	108	23 800	19 100	0,048	1202-TVH
	35	14	7 700	1 730	108	13 300	27 000	0,061	2202-2RS-TVH
	35	14	9 600	2 080	130	22 200	19 600	0,057	2202-TVH
	42	17	9 800	2 260	141	11 200	27 000	0,114	2302-2RS-TVH
	42	17	17 400	3 800	237	17 200	15 600	0,111	2302-TVH
17	40	12	8 100	2 000	124	21 800	17 400	0,073	1203-TVH
	40	16	8 100	2 000	124	11 300	27 000	0,098	2203-2RS-TVH
	40	16	11 800	2 750	171	19 100	17 400	0,088	2203-TVH
	47	14	12 900	3 150	197	17 800	13 300	0,065	1303-TVH
	47	19	12 900	3 150	197	10 100	27 000	0,175	2303-2RS-TVH
	47	19	13 900	3 150	197	17 000	14 900	0,155	2303-TVH
20	47	14	10 100	2 600	161	18 100	15 300	0,116	1204-K-TVH-C3
	47	14	10 100	2 600	161	18 100	15 300	0,118	1204-TVH
	47	18	10 100	2 600	161	9 400	–	0,151	2204-2RS-TVH
	47	18	14 700	3 500	219	16 300	15 600	0,134	2204-TVH
	52	15	12 700	3 300	206	16 100	11 600	0,163	1304-TVH
	52	21	12 700	3 300	206	8 500	–	0,23	2304-2RS-TVH
	52	21	17 600	4 250	265	15 000	13 800	0,206	2304-TVH



Tapered bore

Tapered bore  
with seal 2RS

Mounting dimensions

Dimensions						Mounting dimensions			Calculation factors			
d	r	D <sub>1</sub>	D <sub>2</sub>	d <sub>1</sub>	d <sub>2</sub>	d <sub>a</sub>	D <sub>a</sub>	r <sub>a</sub>	e	Y <sub>1</sub>	Y <sub>2</sub>	Y <sub>0</sub>
	min.	≈	≈	≈	≈	min.	max.	max.				
5	0,3	14,5	–	10,1	–	7,4	16,6	0,3	0,35	1,82	2,82	1,91
6	0,3	14,7	–	10,1	–	8,4	16,6	0,3	0,35	1,82	2,82	1,91
7	0,3	17,1	–	12,4	–	9,4	19,6	0,3	0,33	1,92	2,97	2,01
8	0,3	16,8	–	12,4	–	10,6	19,4	0,3	0,33	1,92	2,97	2,01
9	0,6	20	–	14,5	–	13,2	21,8	0,6	0,32	1,95	3,01	2,04
10	0,6	23,3	–	16,3	–	14,2	25,8	0,6	0,32	1,95	3,02	2,05
	0,6	–	25,2	–	14,1	14,2	25,8	0,6	0,32	1,95	3,02	2,05
	0,6	24	–	15,1	–	14,2	25,8	0,6	0,58	1,09	1,69	1,14
12	0,6	25,1	–	18,2	–	16,2	27,8	0,6	0,37	1,69	2,62	1,77
	0,6	–	27,2	–	16,2	16,2	27,8	0,6	0,37	1,69	2,62	1,77
	0,6	25,9	–	17,1	–	16,2	27,8	0,6	0,53	1,2	1,85	1,25
	1	29,7	–	20,3	–	17,6	31,4	1	0,35	1,8	2,79	1,89
15	0,6	28,8	–	20,2	–	19,2	30,8	0,6	0,34	1,86	2,88	1,95
	0,6	–	30,2	–	19	19,2	30,8	0,6	0,34	1,86	2,88	1,95
	0,6	29,2	–	20,3	–	19,2	30,8	0,6	0,46	1,37	2,13	1,44
	1	–	34,9	–	23,9	20,6	36,4	1	0,35	1,79	2,77	1,88
	1	34,4	–	22,5	–	20,6	36,4	1	0,51	1,23	1,91	1,29
17	0,6	32	–	23,7	–	21,2	35,8	0,6	0,33	1,93	2,99	2,03
	0,6	–	34,3	–	21,6	21,2	35,8	0,6	0,33	1,93	2,99	2,03
	0,6	33,9	–	23,9	–	21,2	35,8	0,6	0,46	1,37	2,12	1,43
	1	37	–	26,7	–	22,6	41,4	1	0,32	1,94	3	2,03
	1	–	39,4	–	23,9	22,6	41,4	1	0,32	1,94	3	2,03
	1	37,3	–	26,2	–	22,6	41,4	1	0,53	1,19	1,85	1,25
20	1	37,8	–	29,2	–	25,6	41,4	1	0,28	2,24	3,46	2,34
	1	37,8	–	29,2	–	25,6	41,4	1	0,28	2,24	3,46	2,34
	1	–	41	–	25,8	25,6	41,4	1	0,28	2,24	3,46	2,34
	1	39,1	–	28	–	25,6	41,4	1	0,44	1,45	2,24	1,51
	1,1	41,5	–	31,6	–	27	45	1	0,29	2,17	3,35	2,27
	1,1	–	44,4	–	27,2	27	45	1	0,29	2,17	3,35	2,27
	1,1	41,2	–	29,1	–	27	45	1	0,51	1,23	1,9	1,29



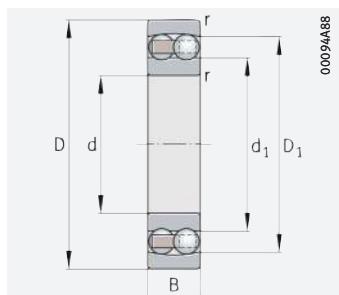


## Self-aligning ball bearings

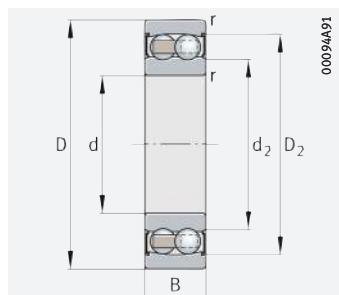
With cylindrical or tapered bore



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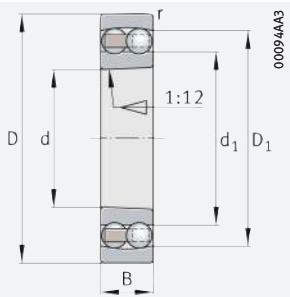
Cylindrical bore



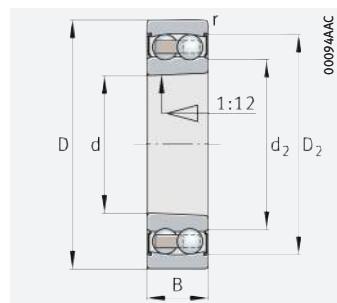
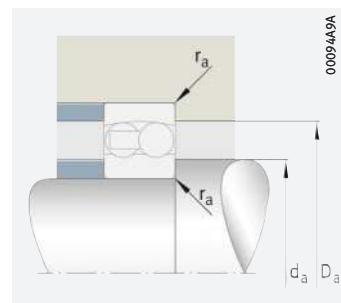
Cylindrical bore with seal 2RS

**d = 25 – 35 mm**

Main dimensions			Basic load ratings		Fatigue limit load	Limiting speed	Speed rating	Mass	Designation
d	D	B	dyn. C <sub>r</sub> N	stat. C <sub>0r</sub> N	C <sub>ur</sub>	n <sub>G</sub> min <sup>-1</sup>	n <sub>θr</sub> min <sup>-1</sup>	m ≈ kg	
25	52	15	12 300	3 250	203	15 500	13 400	0,135	1205-K-TVH-C3
	52	15	12 300	3 250	203	15 500	13 400	0,138	1205-TVH
	52	18	12 300	3 250	203	8 100	–	0,161	2205-2RS-TVH
	52	18	12 300	3 250	203	8 100	–	0,157	2205-K-2RS-TVH-C3
	52	18	17 300	4 400	275	14 400	13 400	0,152	2205-K-TVH-C3
	52	18	17 300	4 400	275	14 400	13 400	0,156	2205-TVH
	62	17	18 300	4 950	310	12 900	10 000	0,254	1305-K-TVH-C3
	62	17	18 300	4 950	310	12 900	10 000	0,258	1305-TVH
	62	24	18 300	4 950	310	7 000	–	0,367	2305-2RS-TVH
	62	24	25 000	6 500	405	12 200	11 900	0,328	2305-K-TVH-C3
	62	24	25 000	6 500	405	12 200	11 900	0,335	2305-TVH
30	62	16	15 900	4 600	285	13 100	11 400	0,217	1206-K-TVH-C3
	62	16	15 900	4 600	285	13 100	11 400	0,221	1206-TVH
	62	20	15 900	4 600	285	6 800	–	0,274	2206-2RS-TVH
	62	20	15 900	4 600	285	6 800	–	0,268	2206-K-2RS-TVH-C3
	62	20	26 000	6 900	425	11 500	11 400	0,246	2206-K-TVH-C3
	62	20	26 000	6 900	425	11 500	11 400	0,252	2206-TVH
	72	19	21 700	6 300	390	11 100	8 700	0,379	1306-K-TVH-C3
	72	19	21 700	6 300	390	11 100	8 700	0,384	1306-TVH
	72	27	21 700	6 300	390	5 900	–	0,554	2306-2RS-TVH
	72	27	32 500	8 700	540	10 200	10 400	0,476	2306-K-TVH-C3
	72	27	32 500	8 700	540	10 200	10 400	0,488	2306-TVH
35	72	17	16 000	5 100	315	11 600	9 800	0,319	1207-K-TVH-C3
	72	17	16 000	5 100	315	11 600	9 800	0,324	1207-TVH
	72	23	16 000	5 100	315	5 600	–	0,442	2207-2RS-TVH
	72	23	16 000	5 100	315	5 600	–	0,432	2207-K-2RS-TVH-C3
	72	23	33 000	8 900	560	9 800	10 300	0,38	2207-K-TVH-C3
	72	23	33 000	8 900	560	9 800	10 300	0,389	2207-TVH
	80	21	25 500	7 800	485	9 700	7 800	0,5	1307-K-TVH-C3
	80	21	25 500	7 800	485	9 700	7 800	0,507	1307-TVH
	80	31	25 500	7 800	485	5 200	–	0,744	2307-2RS-TVH
	80	31	40 500	11 100	690	8 900	9 800	0,657	2307-K-TVH-C3
	80	31	40 500	11 100	690	8 900	9 800	0,675	2307-TVH



Tapered bore

Tapered bore  
with seal 2RS

Mounting dimensions

Dimensions						Mounting dimensions			Calculation factors			
d	r	D <sub>1</sub>	D <sub>2</sub>	d <sub>1</sub>	d <sub>2</sub>	d <sub>a</sub>	D <sub>a</sub>	r <sub>a</sub>	e	Y <sub>1</sub>	Y <sub>2</sub>	Y <sub>0</sub>
		min.	≈	≈	≈	min.	max.	max.				
25	1	43,6	–	33,3	–	30,6	46,4	1	0,27	2,37	3,66	2,48
	1	43,6	–	33,3	–	30,6	46,4	1	0,27	2,37	3,66	2,48
	1	–	45,3	–	30,7	30,6	46,4	1	0,27	2,37	3,66	2,48
	1	–	45,3	–	30,7	30,6	46,4	1	0,27	2,37	3,66	2,48
	1	44,4	–	32,3	–	30,6	46,4	1	0,35	1,78	2,75	1,86
	1	44,4	–	32,3	–	30,6	46,4	1	0,35	1,78	2,75	1,86
	1,1	50,4	–	38,1	–	32	55	1	0,28	2,29	3,54	2,4
	1,1	50,4	–	38,1	–	32	55	1	0,28	2,29	3,54	2,4
	1,1	–	52,4	–	33,5	32	55	1	0,28	2,29	3,54	2,4
	1,1	49,9	–	35,5	–	32	55	1	0,48	1,32	2,04	1,38
	1,1	49,9	–	35,5	–	32	55	1	0,48	1,32	2,04	1,38
30	1	51,6	–	40,1	–	35,6	56,4	1	0,25	2,53	3,91	2,65
	1	51,6	–	40,1	–	35,6	56,4	1	0,25	2,53	3,91	2,65
	1	–	53,3	–	37,3	35,6	56,4	1	0,25	2,53	3,91	2,65
	1	–	53,3	–	37,3	35,6	56,4	1	0,25	2,53	3,91	2,65
	1	53,7	–	38,5	–	35,6	56,4	1	0,3	2,13	3,29	2,23
	1	53,7	–	38,5	–	35,6	56,4	1	0,3	2,13	3,29	2,23
	1,1	58,9	–	45,1	–	37	65	1	0,26	2,39	3,71	2,51
	1,1	58,9	–	45	–	37	65	1	0,26	2,39	3,71	2,51
	1,1	–	62,3	–	40,6	37	65	1	0,26	2,39	3,71	2,51
	1,1	58,8	–	41,5	–	37	65	1	0,45	1,4	2,17	1,47
	1,1	58,8	–	41,5	–	37	65	1	0,45	1,4	2,17	1,47
35	1,1	59,1	–	47,7	–	42	65	1	0,22	2,8	4,34	2,94
	1,1	59,1	–	47,7	–	42	65	1	0,22	2,8	4,34	2,94
	1,1	–	63,4	–	43,5	42	65	1	0,22	2,8	4,34	2,94
	1,1	–	63,4	–	43,5	42	65	1	0,22	2,8	4,34	2,94
	1,1	62,4	–	45,7	–	42	65	1	0,3	2,13	3,29	2,23
	1,1	62,4	–	45,7	–	42	65	1	0,3	2,13	3,29	2,23
	1,5	70,1	–	51,3	–	44	71	1,5	0,26	2,47	3,82	2,59
	1,5	70,1	–	51,3	–	44	71	1,5	0,26	2,47	3,82	2,59
	1,5	–	68,4	–	44,9	44	71	1,5	0,26	2,47	3,82	2,59
	1,5	66,1	–	46,9	–	44	71	1,5	0,47	1,35	2,1	1,42
	1,5	66,1	–	46,9	–	44	71	1,5	0,47	1,35	2,1	1,42



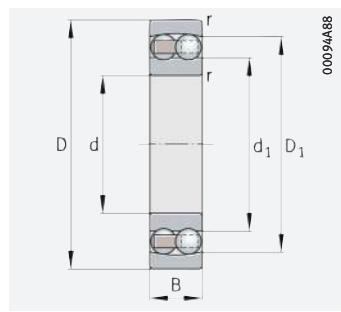


## Self-aligning ball bearings

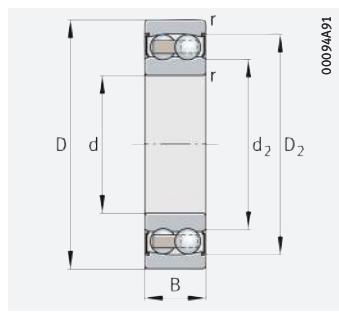
With cylindrical or tapered bore



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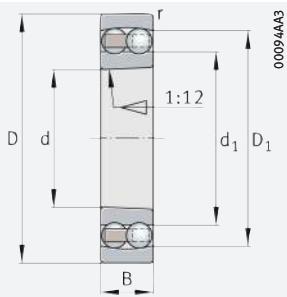


Cylindrical bore

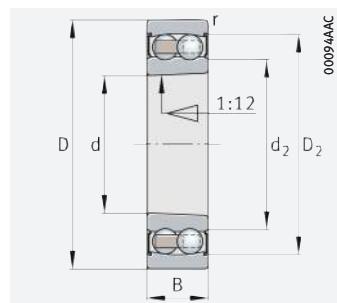
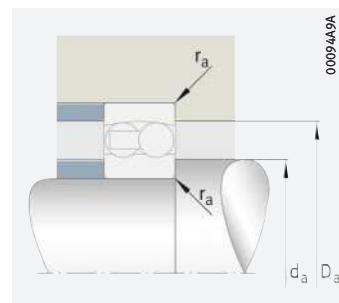
Cylindrical bore  
with seal 2RS

**d = 40 – 50 mm**

Main dimensions			Basic load ratings		Fatigue limit load	Limiting speed	Speed rating	Mass	Designation
d	D	B	dyn. $C_r$ N	stat. $C_{or}$ N	$C_{ur}$ N	$n_G$ min <sup>-1</sup>	$n_{\theta r}$ min <sup>-1</sup>	m ≈ kg	
40	80	18	19 400	6 500	400	10 100	8 600	0,408	1208-K-TVH-C3
	80	18	19 400	6 500	400	10 100	8 600	0,414	1208-TVH
	80	23	19 400	6 500	400	4 950	–	0,528	2208-2RS-TVH
	80	23	19 400	6 500	400	4 950	–	0,517	2208-K-2RS-TVH-C3
	80	23	32 500	9 400	580	8 900	8 700	0,465	2208-K-TVH-C3
	80	23	32 500	9 400	580	8 900	8 700	0,476	2208-TVH
	90	23	30 000	9 600	600	8 600	7 200	0,698	1308-K-TVH-C3
	90	23	30 000	9 600	600	8 600	7 200	0,708	1308-TVH
	90	33	30 000	9 600	600	4 650	–	1,01	2308-2RS-TVH
	90	33	46 000	13 400	830	7 900	8 700	0,899	2308-K-TVH-C3
	90	33	46 000	13 400	830	7 900	8 700	0,922	2308-TVH
45	85	19	22 000	7 300	455	9 300	8 200	0,454	1209-K-TVH-C3
	85	19	22 000	7 300	455	9 300	8 200	0,462	1209-TVH
	85	23	22 000	7 300	455	4 650	–	0,548	2209-2RS-TVH
	85	23	22 000	7 300	455	4 650	–	0,535	2209-K-2RS-TVH-C3
	85	23	28 500	8 900	550	8 600	7 800	0,505	2209-K-TVH-C3
	85	23	28 500	8 900	550	8 600	7 800	0,517	2209-TVH
	100	25	38 500	12 600	780	7 500	6 700	0,939	1309-K-TVH-C3
	100	25	38 500	12 600	780	7 500	6 700	0,953	1309-TVH
	100	36	38 500	12 600	780	4 200	–	1,34	2309-2RS-TVH
	100	36	55 000	16 500	1 030	7 000	8 000	1,19	2309-K-TVH-C3
	100	36	55 000	16 500	1 030	7 000	8 000	1,22	2309-TVH
50	90	20	22 900	8 000	500	8 700	7 700	0,516	1210-K-TVH-C3
	90	20	22 900	8 000	500	8 700	7 700	0,526	1210-TVH
	90	23	22 900	8 000	500	4 250	–	0,606	2210-2RS-TVH
	90	23	22 900	8 000	500	4 250	–	0,593	2210-K-2RS-TVH-C3
	90	23	28 500	9 400	580	8 100	7 100	0,543	2210-K-TVH-C3
	90	23	28 500	9 400	580	8 100	7 100	0,556	2210-TVH
	110	27	42 000	14 100	880	6 900	6 300	1,19	1310-K-TVH-C3
	110	27	42 000	14 100	880	6 900	6 300	1,21	1310-TVH
	110	40	42 000	14 100	880	3 750	–	1,82	2310-2RS-TVH
	110	40	66 000	20 100	1 250	6 300	7 600	1,64	2310-TVH



Tapered bore

Tapered bore  
with seal 2RS

Mounting dimensions

Dimensions						Mounting dimensions			Calculation factors			
d	r	D <sub>1</sub>	D <sub>2</sub>	d <sub>1</sub>	d <sub>2</sub>	d <sub>a</sub>	D <sub>a</sub>	r <sub>a</sub>	e	Y <sub>1</sub>	Y <sub>2</sub>	Y <sub>0</sub>
	min.	≈	≈	≈	≈	min.	max.	max.				
40	1,1	67,3	–	54	–	47	73	1	0,22	2,9	4,49	3,04
	1,1	67,3	–	54	–	47	73	1	0,22	2,9	4,49	3,04
	1,1	–	70,3	–	49,2	47	73	1	0,22	2,9	4,49	3,04
	1,1	–	70,3	–	49,2	47	73	1	0,22	2,9	4,49	3,04
	1,1	70,2	–	52,5	–	47	73	1	0,26	2,43	3,76	2,54
	1,1	70,2	–	52,5	–	47	73	1	0,26	2,43	3,76	2,54
	1,5	74,7	–	57,8	–	49	81	1,5	0,25	2,52	3,9	2,64
	1,5	74,7	–	57,8	–	49	81	1,5	0,25	2,52	3,9	2,64
	1,5	–	77,3	–	51	49	81	1,5	0,25	2,52	3,9	2,64
	1,5	74,5	–	53,7	–	49	81	1,5	0,43	1,45	2,25	1,52
	1,5	74,5	–	53,7	–	49	81	1,5	0,43	1,45	2,25	1,52
45	1,1	72,1	–	57,7	–	52	78	1	0,21	3,04	4,7	3,18
	1,1	72,1	–	57,7	–	52	78	1	0,21	3,04	4,7	3,18
	1,1	–	76	–	53,8	52	78	1	0,21	3,04	4,7	3,18
	1,1	–	76	–	53,8	52	78	1	0,21	3,04	4,7	3,18
	1,1	75,4	–	59	–	52	78	1	0,26	2,43	3,76	2,54
	1,1	75,4	–	59	–	52	78	1	0,26	2,43	3,76	2,54
	1,5	83,5	–	64,1	–	54	91	1,5	0,25	2,5	3,87	2,62
	1,5	83,5	–	64,1	–	54	91	1,5	0,25	2,5	3,87	2,62
	1,5	–	85,8	–	57,5	54	91	1,5	0,25	2,5	3,87	2,62
	1,5	83,6	–	60,1	–	54	91	1,5	0,43	1,48	2,29	1,55
	1,5	83,6	–	60,1	–	54	91	1,5	0,43	1,48	2,29	1,55
50	1,1	77,1	–	62,7	–	57	83	1	0,2	3,17	4,9	3,32
	1,1	77,1	–	62,7	–	57	83	1	0,2	3,17	4,9	3,32
	1,1	–	79	–	60,5	57	83	1	0,2	3,17	4,9	3,32
	1,1	–	79	–	60,5	57	83	1	0,2	3,17	4,9	3,32
	1,1	80,5	–	64	–	57	83	1	0,24	2,61	4,05	2,74
	1,1	80,5	–	64	–	57	83	1	0,24	2,61	4,05	2,74
	2	91,7	–	71,2	–	61	99	2	0,24	2,6	4,03	2,73
	2	91,7	–	71,2	–	61	99	2	0,24	2,6	4,03	2,73
	2	–	95,1	–	65,9	61	99	2	0,24	2,6	4,03	2,73
	2	91,4	–	65,9	–	61	99	2	0,43	1,47	2,27	1,54



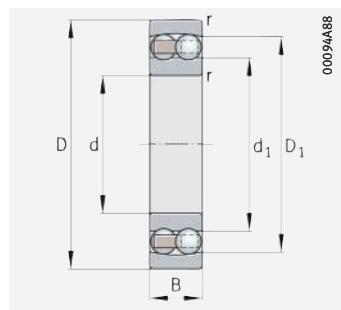


## Self-aligning ball bearings

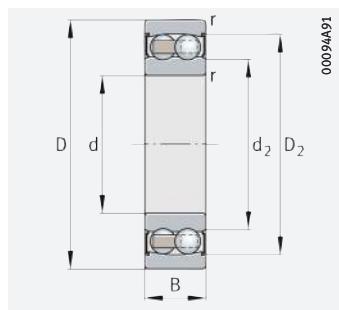
With cylindrical or tapered bore



Kalasanati.com



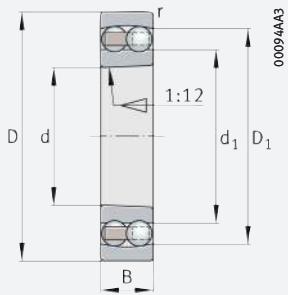
Cylindrical bore



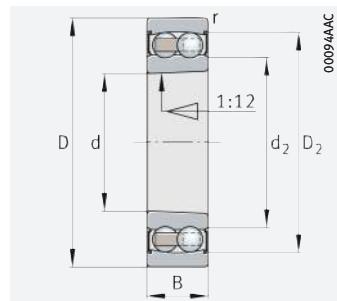
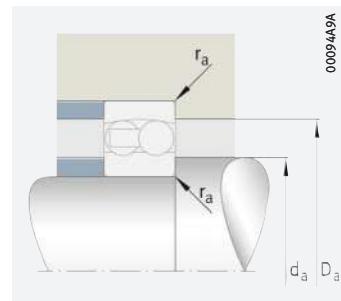
Cylindrical bore with seal 2RS

**d = 55 – 65 mm**

Main dimensions			Basic load ratings		Fatigue limit load	Limiting speed	Speed rating	Mass	Designation
d	D	B	dyn. C <sub>r</sub> N	stat. C <sub>0r</sub> N	C <sub>ur</sub> N	n <sub>G</sub> min <sup>-1</sup>	n <sub>θr</sub> min <sup>-1</sup>	m ≈ kg	
55	100	21	27 000	9 900	620	7 700	6 900	0,682	1211-K-TVH-C3
	100	21	27 000	9 900	620	7 700	6 900	0,693	1211-TVH
	100	25	27 000	9 900	620	3 850	–	0,825	2211-2RS-TVH
	100	25	27 000	9 900	620	3 850	–	0,808	2211-K-2RS-TVH-C3
	100	25	39 000	12 400	770	7 000	6 700	0,73	2211-K-TVH-C3
	100	25	39 000	12 400	770	7 000	6 700	0,746	2211-TVH
	120	29	52 000	17 700	1 100	6 100	5 800	1,55	1311-K-TVH-C3
	120	29	52 000	17 700	1 100	6 100	5 800	1,57	1311-TVH
	120	43	52 000	17 700	1 100	3 450	–	2,28	2311-2RS-TVH
	120	43	77 000	23 800	1 480	5 700	7 100	2,02	2311-K-TVH-C3
	120	43	77 000	23 800	1 480	5 700	7 100	2,07	2311-TVH
60	110	22	30 500	11 400	710	6 900	6 300	0,88	1212-K-TVH-C3
	110	22	30 500	11 400	710	6 900	6 300	0,894	1212-TVH
	110	28	30 500	11 400	710	3 450	–	1,13	2212-2RS-TVH
	110	28	30 500	11 400	710	3 450	–	1,13	2212-K-2RS-TVH-C3
	110	28	48 000	16 300	1 020	6 300	6 400	1,03	2212-K-TVH-C3
	110	28	48 000	16 300	1 020	6 300	6 400	1,06	2212-TVH
	130	31	58 000	20 600	1 280	5 500	5 200	1,94	1312-K-TVH-C3
	130	31	58 000	20 600	1 280	5 500	5 200	1,97	1312-TVH
	130	46	89 000	28 000	1 740	5 200	6 700	2,52	2312-K-TVH-C3
	130	46	89 000	28 000	1 740	5 200	6 700	2,58	2312-TVH
65	120	23	31 000	12 400	770	6 500	5 800	1,13	1213-K-TVH-C3
	120	23	31 000	12 400	770	6 500	5 800	1,14	1213-TVH
	120	31	31 000	12 400	770	3 150	–	1,53	2213-2RS-TVH
	120	31	31 000	12 400	770	3 150	–	1,5	2213-K-2RS-TVH-C3
	120	31	58 000	19 000	1 190	5 600	6 200	1,33	2213-K-TVH-C3
	120	31	58 000	19 000	1 190	5 600	6 200	1,36	2213-TVH
	140	33	63 000	22 700	1 380	5 200	5 100	2,41	1313-K-TVH-C3
	140	33	63 000	22 700	1 380	5 200	5 100	2,44	1313-TVH
	140	48	98 000	32 000	1 980	4 750	6 100	3,16	2313-K-TVH-C3
	140	48	98 000	32 000	1 980	4 750	6 100	3,23	2313-TVH



Tapered bore

Tapered bore  
with seal 2RS

Mounting dimensions

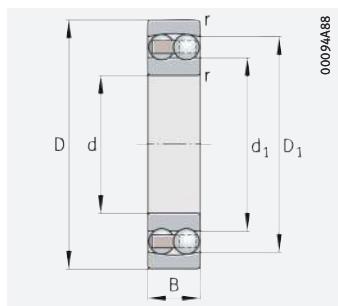
Dimensions						Mounting dimensions			Calculation factors			
d	r	D <sub>1</sub>	D <sub>2</sub>	d <sub>1</sub>	d <sub>2</sub>	d <sub>a</sub>	D <sub>a</sub>	r <sub>a</sub>	e	Y <sub>1</sub>	Y <sub>2</sub>	Y <sub>0</sub>
	min.	≈	≈	≈	≈	min.	max.	max.				
55	1,5	86,4	–	69,5	–	64	91	1,5	0,19	3,31	5,12	3,47
	1,5	86,4	–	69,5	–	64	91	1,5	0,19	3,31	5,12	3,47
	1,5	–	88,2	–	68	64	91	1,5	0,19	3,31	5,12	3,47
	1,5	–	88,2	–	68	64	91	1,5	0,19	3,31	5,12	3,47
	1,5	89,8	–	69,6	–	64	91	1,5	0,22	2,92	4,52	3,06
	1,5	89,8	–	69,6	–	64	91	1,5	0,22	2,92	4,52	3,06
	2	101	–	78	–	66	109	2	0,24	2,66	4,12	2,79
	2	101	–	78	–	66	109	2	0,24	2,66	4,12	2,79
	2	–	106,4	–	70,5	66	109	2	0,24	2,66	4,12	2,79
	2	100,2	–	71,7	–	66	109	2	0,42	1,51	2,33	1,58
	2	100,2	–	71,7	–	66	109	2	0,42	1,51	2,33	1,58
60	1,5	95,2	–	78	–	69	101	1,5	0,18	3,47	5,37	3,64
	1,5	95,2	–	78	–	69	101	1,5	0,18	3,47	5,37	3,64
	1,5	–	99,5	–	70,4	69	101	1,5	0,18	3,47	5,37	3,64
	1,5	–	99,5	–	70,4	69	101	1,5	0,18	3,47	5,37	3,64
	1,5	98,2	–	76,6	–	69	101	1,5	0,23	2,69	4,16	2,82
	1,5	98,2	–	76,6	–	69	101	1,5	0,23	2,69	4,16	2,82
	2,1	112,2	–	87	–	72	118	2,1	0,23	2,77	4,28	2,9
	2,1	112,2	–	87	–	72	118	2,1	0,23	2,77	4,28	2,9
	2,1	108,5	–	77	–	72	118	2,1	0,41	1,55	2,4	1,62
	2,1	108,5	–	77	–	72	118	2,1	0,41	1,55	2,4	1,62
65	1,5	102,7	–	85,2	–	74	111	1,5	0,18	3,57	5,52	3,74
	1,5	102,7	–	85,2	–	74	111	1,5	0,18	3,57	5,52	3,74
	1,5	–	107,8	–	78	74	111	1,5	0,18	3,57	5,52	3,74
	1,5	–	107,8	–	78	74	111	1,5	0,18	3,57	5,52	3,74
	1,5	106,9	–	82,4	–	74	111	1,5	0,23	2,78	4,31	2,92
	1,5	106,9	–	82,4	–	74	111	1,5	0,23	2,78	4,31	2,92
	2,1	118,2	–	92,7	–	77	128	2,1	0,23	2,75	4,26	2,88
	2,1	118,2	–	92,7	–	77	128	2,1	0,23	2,75	4,26	2,88
	2,1	118,3	–	85,6	–	77	128	2,1	0,39	1,62	2,51	1,7
	2,1	118,3	–	85,6	–	77	128	2,1	0,39	1,62	2,51	1,7



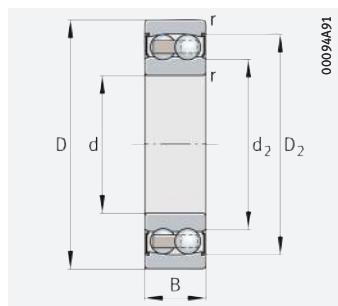


## Self-aligning ball bearings

With cylindrical or tapered bore



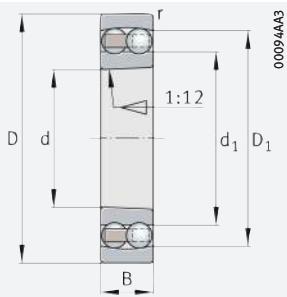
Cylindrical bore

Cylindrical bore  
with seal 2RS

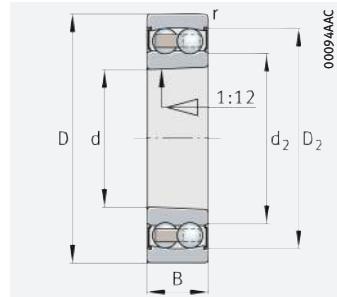
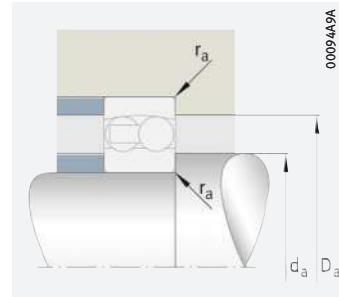
**d = 70 – 85 mm**

Main dimensions			Basic load ratings		Fatigue limit load	Limiting speed	Speed rating	Mass	Designation
d	D	B	dyn. $C_r$ N	stat. $C_{0r}$ N	$C_{ur}$	$n_G$	$n_{\theta r}$	m	
70	125	24	35 000	13 700	850	6 200	5 900	1,23	1214-K-TVH-C3
	125	24	35 000	13 700	850	6 200	5 900	1,25	1214-TVH
	125	31	35 000	13 700	850	3 050	–	1,59	2214-2RS-TVH
	125	31	44 000	16 900	1 050	8 800	5 900	1,69	2214-M
	150	35	75 000	27 500	1 620	7 200	4 950	3,11	1314-M
	150	51	112 000	37 000	2 210	6 600	5 800	4,38	2314-M
75	130	25	39 000	15 600	950	5 700	5 500	1,32	1215-K-TVH-C3
	130	25	39 000	15 600	950	5 700	5 500	1,34	1215-TVH
	130	31	44 500	17 600	1 080	5 600	5 600	1,6	2215-K-TVH-C3
	130	31	44 500	17 600	1 080	5 600	5 600	1,6	2215-TVH
	160	37	80 000	29 500	1 690	6 700	4 750	3,52	1315-K-M-C3
	160	37	80 000	29 500	1 690	6 700	4 750	3,56	1315-M
	160	55	125 000	42 000	2 420	6 100	5 600	5,21	2315-K-M-C3
	160	55	125 000	42 000	2 420	6 100	5 600	5,33	2315-M
80	140	26	40 000	16 800	990	5 300	5 100	1,62	1216-K-TVH-C3
	140	26	40 000	16 800	990	5 300	5 100	1,65	1216-TVH
	140	33	49 500	19 800	1 180	5 300	5 400	1,97	2216-K-TVH-C3
	140	33	49 500	19 800	1 180	5 300	5 400	2,01	2216-TVH
	170	39	89 000	33 000	1 810	6 200	4 500	4,5	1316-K-M-C3
	170	39	89 000	33 000	1 810	6 200	4 500	4,56	1316-M
	170	58	139 000	48 500	2 700	5 700	5 400	6,05	2316-K-M-C3
	170	58	139 000	48 500	2 700	5 700	5 400	6,2	2316-M
85	150	28	49 500	20 600	1 180	4 900	4 950	2,03	1217-K-TVH-C3
	150	28	49 500	20 600	1 180	4 900	4 950	2,07	1217-TVH
	150	36	59 000	23 400	1 340	7 200	5 200	2,73	2217-K-M-C3
	150	36	59 000	23 400	1 340	7 200	5 200	2,79	2217-M
	180	41	99 000	37 500	2 010	5 800	4 300	5,32	1317-K-M-C3
	180	41	99 000	37 500	2 010	5 800	4 300	5,39	1317-M
	180	60	143 000	51 000	2 750	5 400	5 200	7,04	2317-K-M-C3
	180	60	143 000	51 000	2 750	5 400	5 200	7,2	2317-M





Tapered bore

Tapered bore  
with seal 2RS

Mounting dimensions

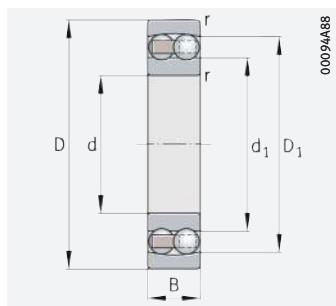
Dimensions						Mounting dimensions			Calculation factors			
d	r	D <sub>1</sub>	D <sub>2</sub>	d <sub>1</sub>	d <sub>2</sub>	d <sub>a</sub>	D <sub>a</sub>	r <sub>a</sub>	e	Y <sub>1</sub>	Y <sub>2</sub>	Y <sub>0</sub>
	min.	≈	≈	≈	≈	min.	max.	max.				
70	1,5	106,1	–	87,2	–	79	116	1,5	0,19	3,36	5,21	3,52
	1,5	106,1	–	87,2	–	79	116	1,5	0,19	3,36	5,21	3,52
	1,5	–	110,8	–	84,7	79	116	1,5	0,19	3,36	5,21	3,52
	1,5	108,9	–	87,6	–	79	116	1,5	0,27	2,34	3,62	2,45
	2,1	126,4	–	97,7	–	82	138	2,1	0,23	2,79	4,32	2,93
	2,1	127,2	–	91,9	–	82	138	2,1	0,38	1,65	2,55	1,73
75	1,5	113,6	–	93,7	–	84	121	1,5	0,19	3,32	5,15	3,48
	1,5	113,6	–	93,7	–	84	121	1,5	0,19	3,32	5,15	3,48
	1,5	114,3	–	93,3	–	84	121	1,5	0,26	2,47	3,82	2,59
	1,5	114,3	–	93,3	–	84	121	1,5	0,26	2,47	3,82	2,59
	2,1	134,8	–	104,8	–	87	148	2,1	0,23	2,77	4,29	2,9
	2,1	134,8	–	104,8	–	87	148	2,1	0,23	2,77	4,29	2,9
	2,1	135,2	–	100,5	–	87	148	2,1	0,38	1,64	2,54	1,72
	2,1	135,2	–	100,5	–	87	148	2,1	0,38	1,64	2,54	1,72
80	2	122,1	–	101,8	–	91	129	2	0,16	3,9	6,03	4,08
	2	122,1	–	102	–	91	129	2	0,16	3,9	6,03	4,08
	2	121	–	99,2	–	91	129	2	0,25	2,48	3,84	2,6
	2	121	–	99,2	–	91	129	2	0,25	2,48	3,84	2,6
	2,1	144,3	–	110,6	–	92	158	2,1	0,22	2,87	4,44	3
	2,1	144,3	–	110,6	–	92	158	2,1	0,22	2,87	4,44	3
	2,1	144,1	–	107,6	–	92	158	2,1	0,37	1,7	2,62	1,78
	2,1	144,1	–	107,6	–	92	158	2,1	0,37	1,7	2,62	1,78
85	2	130,4	–	107,5	–	96	139	2	0,17	3,73	5,78	3,91
	2	130,4	–	107,5	–	96	139	2	0,17	3,73	5,78	3,91
	2	130	–	105,2	–	96	139	2	0,26	2,46	3,81	2,58
	2	130	–	105,2	–	96	139	2	0,26	2,46	3,81	2,58
	3	151,9	–	117,2	–	99	166	2,5	0,22	2,88	4,46	3,02
	3	151,9	–	117,2	–	99	166	2,5	0,22	2,88	4,46	3,02
	3	152,2	–	114,4	–	99	166	2,5	0,37	1,68	2,61	1,76
	3	152,2	–	114,4	–	99	166	2,5	0,37	1,68	2,61	1,76



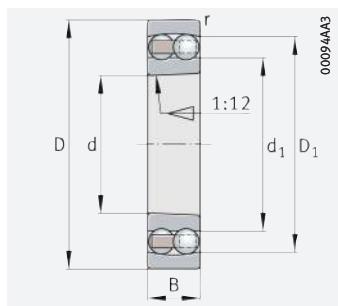


## Self-aligning ball bearings

With cylindrical or tapered bore



Cylindrical bore



Tapered bore

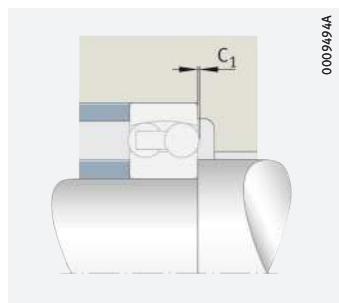
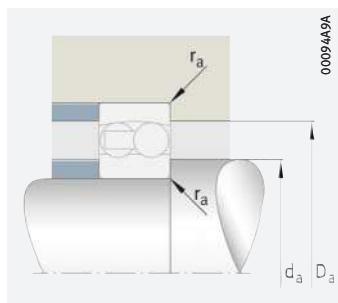
**d = 90 – 105 mm**

Main dimensions			Basic load ratings		Fatigue limit load	Limiting speed	Speed rating	Mass	Designation
d	D	B	dyn. C <sub>r</sub> N	stat. C <sub>0r</sub> N	C <sub>ur</sub>	n <sub>G</sub>	n <sub>θr</sub>	m ≈ kg	► 377 1.12 ► 377 1.13
90	160	30	57 000	23 300	1 300	4 550	4 850	2,48	1218-K-TVH-C3
	160	30	57 000	23 300	1 300	4 550	4 850	2,52	1218-TVH
	160	40	71 000	28 500	1 580	4 400	5 200	3,18	2218-K-TVH-C3
	160	40	71 000	28 500	1 580	4 400	5 200	3,18	2218-TVH
	190	43	109 000	42 500	2 230	5 500	4 200	6,27	1318-K-M-C3
	190	43	109 000	42 500	2 230	5 500	4 200	6,35	1318-M
	190	64	156 000	57 000	3 000	5 100	5 000	8,38	2318-K-M-C3
	190	64	156 000	57 000	3 000	5 100	5 000	8,58	2318-M
95	170	32	64 000	27 000	1 450	6 300	4 600	3,28	1219-K-M-C3
	170	32	64 000	27 000	1 450	6 300	4 600	3,32	1219-M
	170	43	84 000	34 000	1 840	6 100	5 000	4,24	2219-K-M-C3
	170	43	84 000	34 000	1 840	6 100	5 000	4,33	2219-M
	200	45	134 000	50 000	2 550	5 100	4 050	7,2	1319-K-M-C3
	200	45	134 000	50 000	2 550	5 100	4 050	7,29	1319-M
	200	67	167 000	63 000	3 250	4 800	4 750	9,97	2319-K-M-C3
	200	67	167 000	63 000	3 250	4 800	4 750	10,2	2319-M
100	180	34	70 000	29 500	1 550	6 000	4 500	3,94	1220-K-M-C3
	180	34	70 000	29 500	1 550	6 000	4 500	3,99	1220-M
	180	46	98 000	40 000	2 120	5 700	4 900	5,1	2220-K-M-C3
	180	46	98 000	40 000	2 120	5 700	4 900	5,21	2220-M
	215	47	145 000	57 000	2 800	4 700	3 850	8,95	1320-K-M-C3
	215	47	145 000	57 000	2 800	4 700	3 850	9,06	1320-M
	215	73	196 000	78 000	3 900	4 300	4 350	12,7	2320-K-M-C3
	215	73	196 000	78 000	3 900	4 300	4 350	12,9	2320-M
105	190	36	75 000	32 000	1 640	5 700	4 350	4,75	1221-M
	225	49	158 000	64 000	3 100	4 450	3 750	10,3	1321-M

<sup>1)</sup> The ball projection must be taken into consideration when designing the adjacent construction.



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Ball projection  $C_1$ 

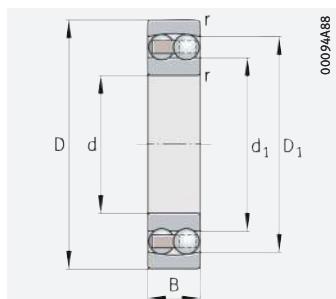
Mounting dimensions

Dimensions					Mounting dimensions			Calculation factors			
d	r	D <sub>1</sub>	d <sub>1</sub>	C <sub>1</sub> <sup>1)</sup>	d <sub>a</sub>	D <sub>a</sub>	r <sub>a</sub>	e	Y <sub>1</sub>	Y <sub>2</sub>	Y <sub>0</sub>
	min.	≈	≈	≈	min.	max.	max.				
90	2	138,7	112,7	–	101	149	2	0,17	3,74	5,79	3,92
	2	138,7	112,7	–	101	149	2	0,17	3,74	5,79	3,92
	2	139,4	111,5	–	101	149	2	0,27	2,33	3,61	2,44
	2	139,4	111,5	–	101	149	2	0,27	2,33	3,61	2,44
	3	159,8	124,4	–	104	176	2,5	0,22	2,83	4,38	2,97
	3	159,8	124,4	–	104	176	2,5	0,22	2,83	4,38	2,97
	3	159,8	115,7	–	104	176	2,5	0,39	1,63	2,53	1,71
	3	159,8	115,7	–	104	176	2,5	0,39	1,63	2,53	1,71
95	2,1	148,2	120,5	–	107	158	2,1	0,17	3,73	5,78	3,91
	2,1	148,2	120,5	–	107	158	2,1	0,17	3,73	5,78	3,91
	2,1	147,9	118,9	–	107	158	2,1	0,27	2,32	3,59	2,43
	2,1	147,9	118,9	–	107	158	2,1	0,27	2,32	3,59	2,43
	3	169,9	127,6	1,6	109	186	2,5	0,23	2,73	4,23	2,86
	3	169,9	127,6	1,6	109	186	2,5	0,23	2,73	4,23	2,86
	3	167,7	121,6	–	109	186	2,5	0,38	1,66	2,57	1,74
	3	167,7	121,6	–	109	186	2,5	0,38	1,66	2,57	1,74
100	2,1	155,2	127,3	–	112	168	2,1	0,18	3,58	5,53	3,75
	2,1	155,2	127,3	–	112	168	2,1	0,18	3,58	5,53	3,75
	2,1	156,9	124,4	–	112	168	2,1	0,27	2,33	3,61	2,44
	2,1	156,9	124,4	–	112	168	2,1	0,27	2,33	3,61	2,44
	3	181,3	135,9	2,4	114	201	2,5	0,24	2,68	4,15	2,81
	3	181,3	135,9	2,4	114	201	2,5	0,24	2,68	4,15	2,81
	3	182,7	130,8	–	114	201	2,5	0,38	1,67	2,58	1,75
	3	182,7	130,8	–	114	201	2,5	0,38	1,67	2,58	1,75
105	2,1	155,2	133,9	–	117	178	2,1	0,18	3,54	5,48	3,71
	3	190,5	143,2	2,5	119	211	2,5	0,23	2,75	4,25	2,88

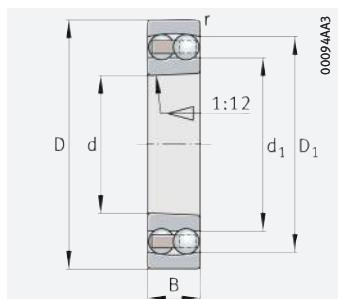


## Self-aligning ball bearings

With cylindrical or tapered bore



Cylindrical bore



Tapered bore

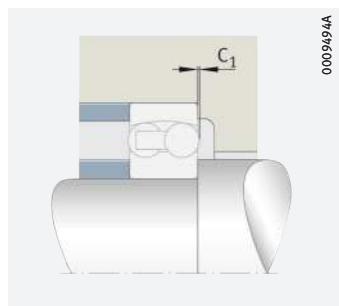
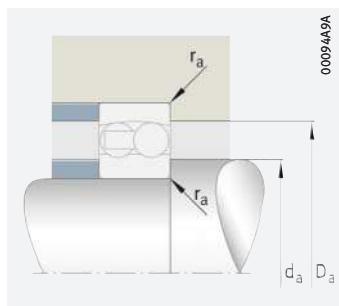
**d = 110 – 150 mm**

Main dimensions			Basic load ratings		Fatigue limit load	Limiting speed	Speed rating	Mass	Designation
d	D	B	dyn. $C_r$ N	stat. $C_{0r}$ N	$C_{ur}$ N	$n_G$ min <sup>-1</sup>	$n_{\theta r}$ min <sup>-1</sup>	m ≈ kg	
<b>110</b>	200	38	89 000	38 000	1 900	5 300	4 250	5,49	<b>1222-K-M-C3</b>
	200	38	89 000	38 000	1 900	5 300	4 250	5,57	<b>1222-M</b>
	200	53	126 000	51 000	2 550	5 000	4 700	7,27	<b>2222-K-M-C3</b>
	200	53	126 000	51 000	2 550	5 000	4 700	7,45	<b>2222-M</b>
	240	50	165 000	71 000	3 300	4 200	3 400	12,2	<b>1322-K-M-C3</b>
	240	50	165 000	71 000	3 300	4 200	3 400	12,3	<b>1322-M</b>
	240	80	221 000	94 000	4 400	3 850	3 900	17,5	<b>2322-K-M-C3</b>
	240	80	221 000	94 000	4 400	3 850	3 900	18,1	<b>2322-M</b>
<b>120</b>	215	42	121 000	52 000	2 500	4 750	4 200	7,13	<b>1224-M</b>
<b>130</b>	230	46	125 000	55 000	2 550	4 450	4 000	8,67	<b>1226-M</b>
<b>140</b>	250	50	163 000	74 000	3 300	3 900	3 650	11,2	<b>1228-M</b>
<b>150</b>	270	54	180 000	86 000	3 700	3 600	3 400	14,6	<b>1230-M</b>

<sup>1)</sup> The ball projection must be taken into consideration when designing the adjacent construction.



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Ball projection  $C_1$ 

Mounting dimensions

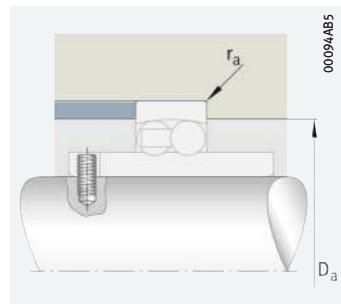
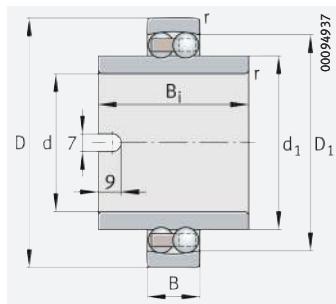
Dimensions					Mounting dimensions			Calculation factors			
d	r	D <sub>1</sub>	d <sub>1</sub>	C <sub>1</sub> <sup>1)</sup>	d <sub>a</sub>	D <sub>a</sub>	r <sub>a</sub>	e	Y <sub>1</sub>	Y <sub>2</sub>	Y <sub>0</sub>
	min.	≈	≈	≈	min.	max.	max.				
<b>110</b>	2,1	173,2	140,2	–	122	188	2,1	0,17	3,61	5,59	3,78
	2,1	173,2	140,2	–	122	188	2,1	0,17	3,61	5,59	3,78
	2,1	174,1	136,9	–	122	188	2,1	0,28	2,23	3,45	2,33
	2,1	174,1	136,9	–	122	188	2,1	0,28	2,23	3,45	2,33
	3	202,5	154,5	2,7	124	226	2,5	0,23	2,79	4,32	2,92
	3	202,5	154,5	2,7	124	226	2,5	0,23	2,79	4,32	2,92
	3	201,8	145,5	–	124	226	2,5	0,37	1,69	2,62	1,77
	3	201,8	145,5	–	124	226	2,5	0,37	1,69	2,62	1,77
<b>120</b>	2,1	187,3	149	1,8	132	203	2,1	0,2	3,11	4,81	3,25
<b>130</b>	3	200	161,5	0,6	144	216	2,5	0,19	3,24	5,02	3,4
<b>140</b>	3	220,5	175	2,7	154	236	2,5	0,21	3,05	4,71	3,19
<b>150</b>	3	237,9	186,7	3,8	164	256	2,5	0,22	2,9	4,49	3,04





## Self-aligning ball bearings

With extended inner ring



Mounting dimensions

**d = 20 – 60 mm**

Main dimensions			Basic load ratings		Fatigue limit load	Limiting speed	Mass	Designation
d	D	B	dyn. C <sub>r</sub> N	stat. C <sub>0r</sub> N	C <sub>ur</sub> N	n <sub>G</sub> min <sup>-1</sup>	m ≈ kg	► 377   1.12 ► 377   1.13
20	47	14	10 100	2 600	161	18 100	0,186	11204-TVH
25	52	15	12 300	3 250	203	15 500	0,22	11205-TVH
30	62	16	15 900	4 600	285	13 100	0,35	11206-TVH
35	72	17	16 000	5 100	315	11 600	0,54	11207-TVH
40	80	18	19 400	6 500	400	10 100	0,72	11208-TVH
45	85	19	22 000	7 300	455	9 300	0,77	11209-TVH
50	90	20	22 900	8 000	500	8 700	0,85	11210-TVH
55	100	21	27 000	9 900	620	7 700	1,17	11211-TVH
60	110	22	30 500	11 400	710	6 900	1,5	11212-TVH



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Dimensions					Mounting dimensions		Calculation factors			
d	r	B <sub>i</sub>	D <sub>1</sub>	d <sub>1</sub>	D <sub>a</sub>	r <sub>a</sub>	e	Y <sub>1</sub>	Y <sub>2</sub>	Y <sub>0</sub>
	min.	≈	≈	≈	max.	max.				
<b>20</b>	1	40	37,8	29,2	41,4	1	0,28	2,24	3,46	2,34
<b>25</b>	1	44	43,6	33,3	46,4	1	0,27	2,37	3,66	2,48
<b>30</b>	1	48	51,6	40,1	56,4	1	0,25	2,53	3,91	2,65
<b>35</b>	1,1	52	59,1	47,7	65	1	0,22	2,8	4,34	2,94
<b>40</b>	1,1	56	67,3	54	73	1	0,22	2,9	4,49	3,04
<b>45</b>	1,1	58	72,1	57,7	78	1	0,21	3,04	4,7	3,18
<b>50</b>	1,1	58	77,1	62,7	83	1	0,2	3,17	4,9	3,32
<b>55</b>	1,5	60	86,4	69,5	91	1,5	0,19	3,31	5,12	3,47
<b>60</b>	1,5	62	95,2	78	101	1,5	0,18	3,47	5,37	3,64



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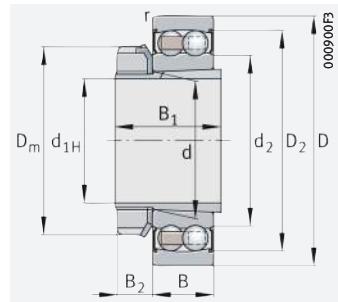
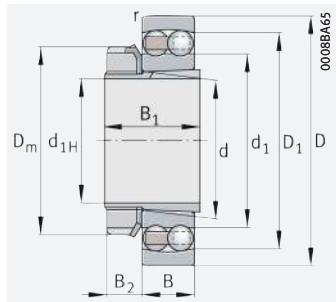


# Self-aligning ball bearings

With adapter sleeve



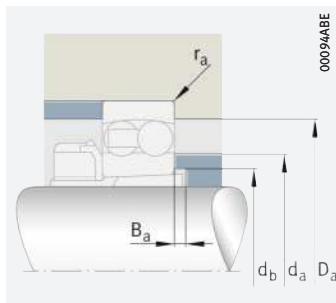
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With seal 2RS

**d<sub>1H</sub> = 17 – 45 mm**

Main dimensions				Basic load ratings		Fatigue limit load	Limiting speed	Speed rating	Mass m		Designation ► 377 1.12 ► 377 1.13	
d <sub>1H</sub>	d	D	B	dyn. C <sub>r</sub> N	stat. C <sub>0r</sub> N	C <sub>ur</sub>	n <sub>G</sub> min <sup>-1</sup>	n <sub>θr</sub> min <sup>-1</sup>	Bearing ≈ kg	Adapter sleeve ≈ kg	Bearing	Adapter sleeve
<b>17</b>	20	47	14	10 100	2 600	161	18 100	15 300	0,116	0,04	<b>1204-K-TVH-C3</b>	<b>H204</b>
<b>20</b>	25	52	15	12 300	3 250	203	15 500	13 400	0,135	0,07	<b>1205-K-TVH-C3</b>	<b>H205</b>
	25	52	18	12 300	3 250	203	8 100	–	0,157	0,07	<b>2205-K-2RS-TVH-C3</b>	<b>H305</b>
	25	52	18	17 300	4 400	275	14 400	13 400	0,152	0,07	<b>2205-K-TVH-C3</b>	<b>H305</b>
	25	62	17	18 300	4 950	310	12 900	10 000	0,254	0,07	<b>1305-K-TVH-C3</b>	<b>H305</b>
	25	62	24	25 000	6 500	405	12 200	11 900	0,328	0,09	<b>2305-K-TVH-C3</b>	<b>H2305</b>
<b>25</b>	30	62	16	15 900	4 600	285	13 100	11 400	0,217	0,1	<b>1206-K-TVH-C3</b>	<b>H206</b>
	30	62	20	15 900	4 600	285	6 800	–	0,268	0,11	<b>2206-K-2RS-TVH-C3</b>	<b>H306</b>
	30	62	20	26 000	6 900	425	11 500	11 400	0,246	0,11	<b>2206-K-TVH-C3</b>	<b>H306</b>
	30	72	19	21 700	6 300	390	11 100	8 700	0,379	0,11	<b>1306-K-TVH-C3</b>	<b>H306</b>
	30	72	27	32 500	8 700	540	10 200	10 400	0,476	0,13	<b>2306-K-TVH-C3</b>	<b>H2306</b>
<b>30</b>	35	72	17	16 000	5 100	315	11 600	9 800	0,319	0,136	<b>1207-K-TVH-C3</b>	<b>H207</b>
	35	72	23	16 000	5 100	315	5 600	–	0,432	0,153	<b>2207-K-2RS-TVH-C3</b>	<b>H307</b>
	35	72	23	33 000	8 900	560	9 800	10 300	0,38	0,153	<b>2207-K-TVH-C3</b>	<b>H307</b>
	35	80	21	25 500	7 800	485	9 700	7 800	0,5	0,153	<b>1307-K-TVH-C3</b>	<b>H307</b>
	35	80	31	40 500	11 100	690	8 900	9 800	0,657	0,16	<b>2307-K-TVH-C3</b>	<b>H2307</b>
<b>35</b>	40	80	18	19 400	6 500	400	10 100	8 600	0,408	0,177	<b>1208-K-TVH-C3</b>	<b>H208</b>
	40	80	23	19 400	6 500	400	4 950	–	0,517	0,192	<b>2208-K-2RS-TVH-C3</b>	<b>H308</b>
	40	80	23	32 500	9 400	580	8 900	8 700	0,465	0,192	<b>2208-K-TVH-C3</b>	<b>H308</b>
	40	90	23	30 000	9 600	600	8 600	7 200	0,698	0,192	<b>1308-K-TVH-C3</b>	<b>H308</b>
	40	90	33	46 000	13 400	830	7 900	8 700	0,899	0,23	<b>2308-K-TVH-C3</b>	<b>H2308</b>
<b>40</b>	45	85	19	22 000	7 300	455	9 300	8 200	0,454	0,23	<b>1209-K-TVH-C3</b>	<b>H209</b>
	45	85	23	22 000	7 300	455	4 650	–	0,535	0,253	<b>2209-K-2RS-TVH-C3</b>	<b>H309</b>
	45	85	23	28 500	8 900	550	8 600	7 800	0,505	0,253	<b>2209-K-TVH-C3</b>	<b>H309</b>
	45	100	25	38 500	12 600	780	7 500	6 700	0,939	0,253	<b>1309-K-TVH-C3</b>	<b>H309</b>
	45	100	36	55 000	16 500	1 030	7 000	8 000	1,19	0,298	<b>2309-K-TVH-C3</b>	<b>H2309</b>
<b>45</b>	50	90	20	22 900	8 000	500	8 700	7 700	0,516	0,276	<b>1210-K-TVH-C3</b>	<b>H210</b>
	50	90	23	22 900	8 000	500	4 250	–	0,593	0,306	<b>2210-K-2RS-TVH-C3</b>	<b>H310</b>
	50	90	23	28 500	9 400	580	8 100	7 100	0,543	0,306	<b>2210-K-TVH-C3</b>	<b>H310</b>
	50	110	27	42 000	14 100	880	6 900	6 300	1,19	0,306	<b>1310-K-TVH-C3</b>	<b>H310</b>



Mounting dimensions

Dimensions									Mounting dimensions					Calculation factors			
d <sub>1H</sub>	r	D <sub>1</sub>	D <sub>2</sub>	d <sub>1</sub>	d <sub>2</sub>	D <sub>m</sub>	B <sub>1</sub>	B <sub>2</sub>	d <sub>a</sub>	D <sub>a</sub>	d <sub>b</sub>	B <sub>a</sub>	r <sub>a</sub>	e	Y <sub>1</sub>	Y <sub>2</sub>	Y <sub>0</sub>
min.	≈	≈	≈	≈	≈	≈	≈	≈	max.	max.	min.	min.	max.				
17	1	37,8	–	29,2	–	32	24	7	27	41,4	23	5	1	0,28	2,24	3,46	2,34
20	1	43,6	–	33,3	–	38	26	8,25	32	46,4	28	5	1	0,27	2,37	3,66	2,48
	1	–	45,3	–	30,7	38	29	8,25	32	46,4	28	5	1	0,27	2,37	3,66	2,48
	1	44,4	–	32,3	–	38	29	8,25	32	46,4	28	5	1	0,35	1,78	2,75	1,86
	1,1	50,4	–	38,1	–	38	29	8,25	35	55	28	6	1	0,28	2,29	3,54	2,4
	1,1	49,9	–	35,5	–	38	35	8,25	34	55	30	5	1	0,48	1,32	2,04	1,38
25	1	51,6	–	40,1	–	45	27	8,25	38	56,4	33	5	1	0,25	2,53	3,91	2,65
	1	–	53,3	–	37,3	45	31	8,25	38	56,4	33	5	1	0,25	2,53	3,91	2,65
	1	53,7	–	38,5	–	45	31	8,25	38	56,4	33	5	1	0,3	2,13	3,29	2,23
	1,1	58,9	–	45,1	–	45	31	8,25	42	65	33	6	1	0,26	2,39	3,71	2,51
	1,1	58,8	–	41,5	–	45	38	8,25	40	65	35	5	1	0,45	1,4	2,17	1,47
30	1,1	59,1	–	47,7	–	52	29	9,25	45	65	38	5	1	0,22	2,8	4,34	2,94
	1,1	–	63,4	–	43,5	52	35	9,25	45	65	38	5	1	0,22	2,8	4,34	2,94
	1,1	62,4	–	45,7	–	52	35	9,25	44	65	39	5	1	0,3	2,13	3,29	2,23
	1,5	70,1	–	51,3	–	52	35	9,25	49	71	39	8	1,5	0,26	2,47	3,82	2,59
	1,5	66,1	–	46,9	–	52	43	9,25	45	71	40	5	1,5	0,47	1,35	2,1	1,42
35	1,1	67,3	–	54	–	58	31	10,25	52	73	43	5	1	0,22	2,9	4,49	3,04
	1,1	–	70,3	–	49,2	58	36	10,25	52	73	43	5	1	0,22	2,9	4,49	3,04
	1,1	70,2	–	52,5	–	58	36	10,25	50	73	44	5	1	0,26	2,43	3,76	2,54
	1,5	74,7	–	57,8	–	58	36	10,25	55	81	44	5	1,5	0,25	2,52	3,9	2,64
	1,5	74,5	–	53,7	–	58	46	10,25	51	81	45	5	1,5	0,43	1,45	2,25	1,52
40	1,1	72,1	–	57,7	–	65	33	11,25	57	78	48	5	1	0,21	3,04	4,7	3,18
	1,1	–	76	–	53,8	65	39	11,25	57	78	48	5	1	0,21	3,04	4,7	3,18
	1,1	75,4	–	59	–	65	39	11,25	56	78	50	8	1	0,26	2,43	3,76	2,54
	1,5	83,5	–	64,1	–	65	39	11,25	61	91	50	5	1,5	0,25	2,5	3,87	2,62
	1,5	83,6	–	60,1	–	65	50	11,25	57	91	50	5	1,5	0,43	1,48	2,29	1,55
45	1,1	77,1	–	62,7	–	70	35	12,25	62	83	53	5	1	0,2	3,17	4,9	3,32
	1,1	–	79	–	60,5	70	42	12,25	62	83	53	5	1	0,2	3,17	4,9	3,32
	1,1	80,5	–	64	–	70	42	12,25	61	83	55	10	1	0,24	2,61	4,05	2,74
	2	91,7	–	71,2	–	70	42	12,25	68	99	55	5	2	0,24	2,6	4,03	2,73

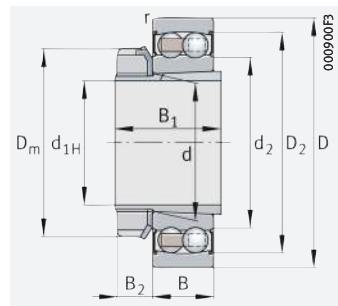
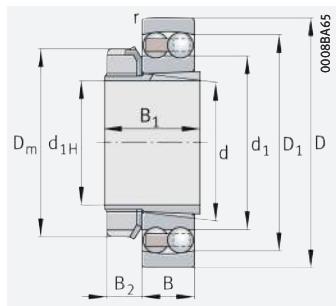


# Self-aligning ball bearings

With adapter sleeve



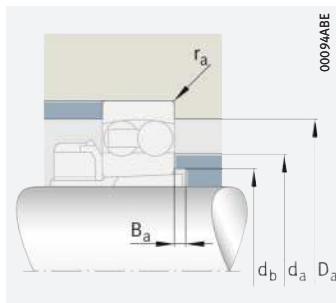
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With seal 2RS

$$d_{1H} = 50 - 75 \text{ mm}$$

Main dimensions				Basic load ratings		Fatigue limit load	Limiting speed	Speed rating	Mass m		Designation	
$d_{1H}$	d	D	B	dyn. $C_r$ N	stat. $C_{0r}$ N	$C_{ur}$ N	$n_G$ min $^{-1}$	$n_{\theta r}$ min $^{-1}$	Bearing $\approx$ kg	Adapter sleeve $\approx$ kg	Bearing	Adapter sleeve
50	55	100	21	27 000	9 900	620	7 700	6 900	0,682	0,319	1211-K-TVH-C3	H211
	55	100	25	27 000	9 900	620	3 850	—	0,808	0,358	2211-K-2RS-TVH-C3	H311
	55	100	25	39 000	12 400	770	7 000	6 700	0,73	0,358	2211-K-TVH-C3	H311
	55	120	29	52 000	17 700	1 100	6 100	5 800	1,55	0,358	1311-K-TVH-C3	H311
	55	120	43	77 000	23 800	1 480	5 700	7 100	2,02	0,435	2311-K-TVH-C3	H2311
55	60	110	22	30 500	11 400	710	6 900	6 300	0,88	0,35	1212-K-TVH-C3	H212
	60	110	28	30 500	11 400	710	3 450	—	1,13	0,401	2212-K-2RS-TVH-C3	H312
	60	110	28	48 000	16 300	1 020	6 300	6 400	1,03	0,401	2212-K-TVH-C3	H312
	60	130	31	58 000	20 600	1 280	5 500	5 200	1,94	0,401	1312-K-TVH-C3	H312
	60	130	46	89 000	28 000	1 740	5 200	6 700	2,52	0,493	2312-K-TVH-C3	H2312
60	65	120	23	31 000	12 400	770	6 500	5 800	1,13	0,4	1213-K-TVH-C3	H213
	65	120	31	31 000	12 400	770	3 150	—	1,5	0,471	2213-K-2RS-TVH-C3	H313
	65	120	31	58 000	19 000	1 190	5 600	6 200	1,33	0,471	2213-K-TVH-C3	H313
	65	140	33	63 000	22 700	1 380	5 200	5 100	2,41	0,471	1313-K-TVH-C3	H313
	65	140	48	98 000	32 000	1 980	4 750	6 100	3,16	0,57	2313-K-TVH-C3	H2313
	70	125	24	35 000	13 700	850	6 200	5 900	1,23	0,63	1214-K-TVH-C3	H214
65	75	130	25	39 000	15 600	950	5 700	5 500	1,32	0,71	1215-K-TVH-C3	H215
	75	130	31	44 500	17 600	1 080	5 600	5 600	1,6	0,86	2215-K-TVH-C3	H315
	75	160	37	80 000	29 500	1 690	6 700	4 750	3,52	1,06	1315-K-M-C3	H315
	75	160	55	125 000	42 000	2 420	6 100	5 600	5,21	0,89	2315-K-M-C3	H2315
70	80	140	26	40 000	16 800	990	5 300	5 100	1,62	0,89	1216-K-TVH-C3	H216
	80	140	33	49 500	19 800	1 180	5 300	5 400	1,97	1,06	2216-K-TVH-C3	H316
	80	170	39	89 000	33 000	1 810	6 200	4 500	4,5	1,06	1316-K-M-C3	H316
	80	170	58	139 000	48 500	2 700	5 700	5 400	6,05	1,31	2316-K-M-C3	H2316
75	85	150	28	49 500	20 600	1 180	4 900	4 950	2,03	1,03	1217-K-TVH-C3	H217
	85	150	36	59 000	23 400	1 340	7 200	5 200	2,73	1,21	2217-K-M-C3	H317
	85	180	41	99 000	37 500	2 010	5 800	4 300	5,32	1,21	1317-K-M-C3	H317
	85	180	60	143 000	51 000	2 750	5 400	5 200	7,04	1,47	2317-K-M-C3	H2317



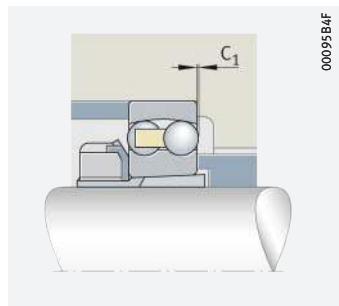
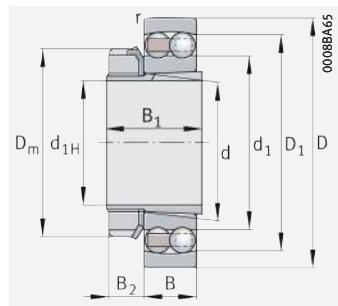
Mounting dimensions

Dimensions										Mounting dimensions					Calculation factors			
d <sub>1H</sub>	r	D <sub>1</sub>	D <sub>2</sub>	d <sub>1</sub>	d <sub>2</sub>	D <sub>m</sub>	B <sub>1</sub>	B <sub>2</sub>		d <sub>a</sub>	D <sub>a</sub>	d <sub>b</sub>	B <sub>a</sub>	r <sub>a</sub>	e	Y <sub>1</sub>	Y <sub>2</sub>	Y <sub>0</sub>
	min.	≈	≈	≈	≈			≈		max.	max.	min.	min.	max.				
50	1,5	86,4	–	69,5	–	75	37	12,5		69	91	60	6	1,5	0,19	3,31	5,12	3,47
	1,5	–	88,2	–	68	75	45	12,5		69	91	60	6	1,5	0,19	3,31	5,12	3,47
	1,5	89,8	–	69,6	–	75	45	12,5		68	91	60	10	1,5	0,22	2,92	4,52	3,06
	2	101	–	78	–	75	45	12,5		74	109	60	6	2	0,24	2,66	4,12	2,79
	2	100,2	–	71,7	–	75	59	12,5		69	109	61	6	2	0,42	1,51	2,33	1,58
55	1,5	95,2	–	78	–	80	38	12,5		75	101	64	5	1,5	0,18	3,47	5,37	3,64
	1,5	–	99,5	–	70,4	80	47	12,5		75	101	64	5	1,5	0,18	3,47	5,37	3,64
	1,5	98,2	–	76,6	–	80	47	12,5		73	101	65	8	1,5	0,23	2,69	4,16	2,82
	2,1	112,2	–	87	–	80	47	12,5		83	118	65	5	2,1	0,23	2,77	4,28	2,9
	2,1	108,5	–	77	–	80	62	12,5		74	118	66	5	2,1	0,41	1,55	2,4	1,62
60	1,5	102,7	–	85,2	–	85	40	13,5		83	111	70	5	1,5	0,18	3,57	5,52	3,74
	1,5	–	107,8	–	78	85	50	13,5		83	111	70	5	1,5	0,18	3,57	5,52	3,74
	1,5	106,9	–	82,4	–	85	50	13,5		79	111	70	8	1,5	0,23	2,78	4,31	2,92
	2,1	118,2	–	92,7	–	85	50	13,5		89	128	70	5	2,1	0,23	2,75	4,26	2,88
	2,1	118,3	–	85,6	–	85	65	13,5		82	128	72	5	2,1	0,39	1,62	2,51	1,7
	1,5	106,1	–	87,2	–	92	41	13,5		86	116	75	5	1,5	0,19	3,36	5,21	3,52
65	1,5	113,6	–	93,7	–	98	43	14,5		92	121	80	5	1,5	0,19	3,32	5,15	3,48
	1,5	114,3	–	93,3	–	98	55	14,5		90	121	80	12	1,5	0,26	2,47	3,82	2,59
	2,1	134,8	–	104,8	–	98	55	14,5		100	148	80	5	2,1	0,23	2,77	4,29	2,9
	2,1	135,2	–	100,5	–	98	73	14,5		94	148	82	5	2,1	0,38	1,64	2,54	1,72
70	2	122,1	–	101,8	–	105	46	16,75		99	129	85	5	2	0,16	3,9	6,03	4,08
	2	121	–	99,2	–	105	59	16,75		96	129	85	12	2	0,25	2,48	3,84	2,6
	2,1	144,3	–	110,6	–	105	59	16,75		107	158	85	5	2,1	0,22	2,87	4,44	3
	2,1	144,1	–	107,6	–	105	78	16,75		100	158	88	5	2,1	0,37	1,7	2,62	1,78
75	2	130,4	–	107,5	–	110	50	17,75		105	139	90	6	2	0,17	3,73	5,78	3,91
	2	130	–	105,2	–	110	63	17,75		102	139	91	12	2	0,26	2,46	3,81	2,58
	3	151,9	–	117,2	–	110	63	17,75		114	166	91	6	2,5	0,22	2,88	4,46	3,02
	3	152,2	–	114,4	–	110	82	17,75		106	166	94	6	2,5	0,37	1,68	2,61	1,76



## Self-aligning ball bearings

With adapter sleeve



Ball projection  $C_1$ <sup>1)</sup>

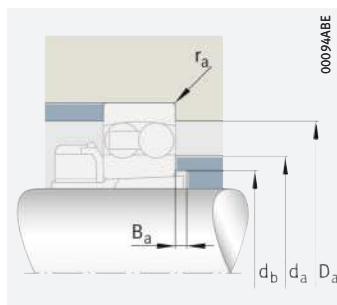
**$d_{1H} = 80 - 100 \text{ mm}$**

Main dimensions				Basic load ratings		Fatigue limit load	Limiting speed	Speed rating	Mass		Designation	
$d_{1H}$	$d$	D	B	dyn. $C_r$ N	stat. $C_{0r}$ N	$C_{ur}$	$n_G$	$n_{\theta r}$	Bearing $\approx \text{kg}$	Adapter sleeve $\approx \text{kg}$	Bearing	Adapter sleeve
80	90	160	30	57 000	23 300	1 300	4 550	4 850	2,48	1,21	1218-K-TVH-C3	H218
	90	160	40	71 000	28 500	1 580	4 400	5 200	3,18	1,41	2218-K-TVH-C3	H318
	90	190	43	109 000	42 500	2 230	5 500	4 200	6,27	1,41	1318-K-M-C3	H318
	90	190	64	156 000	57 000	3 000	5 100	5 000	8,38	1,71	2318-K-M-C3	H2318
85	95	170	32	64 000	27 000	1 450	6 300	4 600	3,28	1,39	1219-K-M-C3	H219
	95	170	43	84 000	34 000	1 840	6 100	5 000	4,24	1,58	2219-K-M-C3	H319
	95	200	45	134 000	50 000	2 550	5 100	4 050	7,2	1,58	1319-K-M-C3	H319
	95	200	67	167 000	63 000	3 250	4 800	4 750	9,97	1,95	2319-K-M-C3	H2319
90	100	180	34	70 000	29 500	1 550	6 000	4 500	3,94	1,52	1220-K-M-C3	H220
	100	180	46	98 000	40 000	2 120	5 700	4 900	5,1	1,76	2220-K-M-C3	H320
	100	215	47	145 000	57 000	2 800	4 700	3 850	8,95	1,76	1320-K-M-C3	H320
	100	215	73	196 000	78 000	3 900	4 300	4 350	12,7	2,2	2320-K-M-C3	H2320
100	110	200	38	89 000	38 000	1 900	5 300	4 250	5,49	1,95	1222-K-M-C3	H222
	110	200	53	126 000	51 000	2 550	5 000	4 700	7,27	2,25	2222-K-M-C3	H322
	110	240	50	165 000	71 000	3 300	4 200	3 400	12,2	2,25	1322-K-M-C3	H322
	110	240	80	221 000	94 000	4 400	3 850	3 900	17,5	2,78	2322-K-M-C3	H2322

<sup>1)</sup> The ball projection must be taken into consideration when designing the adjacent construction.



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Mounting dimensions

Dimensions									Mounting dimensions					Calculation factors			
d <sub>1H</sub>	r	D <sub>1</sub>	d <sub>1</sub>	D <sub>m</sub>	B <sub>1</sub>	B <sub>2</sub>	C <sub>1</sub> <sup>1)</sup>	d <sub>a</sub>	D <sub>a</sub>	d <sub>b</sub>	B <sub>a</sub>	r <sub>a</sub>	e	Y <sub>1</sub>	Y <sub>2</sub>	Y <sub>0</sub>	
min.	≈	≈	≈			≈		max.	max.	min.	min.	max.					
<b>80</b>	2	138,7	112,7	120	52	17,75	–	110	149	95	6	2	0,17	3,74	5,79	3,92	
	2	139,4	111,5	120	65	17,75	–	108	149	96	10	2	0,27	2,33	3,61	2,44	
	3	159,8	124,4	120	65	17,75	–	120	176	96	6	2,5	0,22	2,83	4,38	2,97	
	3	159,8	115,7	120	86	17,75	–	112	176	100	6	2,5	0,39	1,63	2,53	1,71	
<b>85</b>	2,1	148,2	120,5	125	55	18,75	–	117	158	100	7	2,1	0,17	3,73	5,78	3,91	
	2,1	147,9	118,9	125	68	18,75	–	114	158	102	9	2,1	0,27	2,32	3,59	2,43	
	3	169,9	127,6	125	68	18,75	1,6	126	186	102	7	2,5	0,23	2,73	4,23	2,86	
	3	167,7	121,6	125	90	18,75	–	117	186	105	7	2,5	0,38	1,66	2,57	1,74	
<b>90</b>	2,1	155,2	127,3	130	58	19,75	–	124	168	106	7	2,1	0,18	3,58	5,53	3,75	
	2,1	156,9	124,4	130	71	19,75	–	120	168	108	8	2,1	0,27	2,33	3,61	2,44	
	3	181,3	135,9	130	71	19,75	2,4	132	201	108	7	2,5	0,24	2,68	4,15	2,81	
	3	182,7	130,8	130	97	19,75	–	125	201	110	7	2,5	0,38	1,67	2,58	1,75	
<b>100</b>	2,1	173,2	140,2	145	63	20,75	–	138	188	116	7	2,1	0,17	3,61	5,59	3,78	
	2,1	174,1	136,9	145	77	20,75	–	132	188	118	6	2,1	0,28	2,23	3,45	2,33	
	3	202,5	154,5	145	77	20,75	2,7	150	226	118	9	2,5	0,23	2,79	4,32	2,92	
	3	201,8	145,5	145	105	20,75	–	139	226	121	7	2,5	0,37	1,69	2,62	1,77	





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